



**TIVP Series
IsoVu™ Measurement System
User Manual**

Supports MSO 4/5/6 Series Firmware version 1.28 and above

Register now!
Click the following link to protect your product.
www.tek.com/register

Copyright © Tektronix. All rights reserved. Licensed software products are owned by Tektronix or its subsidiaries or suppliers, and are protected by national copyright laws and international treaty provisions. Tektronix products are covered by U.S. and foreign patents, issued and pending. Information in this publication supersedes that in all previously published material. Specifications and price change privileges reserved.

TEKTRONIX and TEK are registered trademarks of Tektronix, Inc.

Contacting Tektronix

Tektronix, Inc.

14150 SW Karl Braun Drive

P.O. Box 500

Beaverton, OR 97077

USA

For product information, sales, service, and technical support:

- In North America, call 1-800-833-9200.
- Worldwide, visit www.tek.com to find contacts in your area.

Table of Contents

List of Figures.....	5
List of Tables.....	6
Warranty.....	7
TEKTRONIX END USER LICENSE AGREEMENT.....	8
Third Party Software Licenses.....	12
Important safety information.....	14
General safety summary.....	14
To avoid fire or personal injury.....	14
Sensor tip cables.....	15
Terms in this manual.....	15
Symbols and terms on the product.....	15
Compliance information.....	16
Safety compliance.....	16
Environmental considerations.....	17
Preface.....	18
Key features.....	18
Laser certification.....	18
Product description.....	19
Compensation box.....	19
Sensor head.....	19
Sensor tip cables.....	19
Models.....	20
Supported oscilloscopes.....	20
Accessories.....	20
Standard accessories.....	20
Optional accessories.....	21
Getting started.....	23
Operating considerations.....	23
Measurement system handling best practices.....	23
Environmental requirements.....	24
Clearance requirements.....	25
Controls and indicators.....	26
Cable flags.....	26
Sensor tip cable.....	26
Connecting to a circuit.....	27
Self-calibration.....	29
AutoZero.....	30
Menu button.....	31
Ranges.....	31
Auto Range.....	32
Selecting a sensor tip cable.....	32
Deskew.....	32
Input offset.....	32
Input coupling AC or DC.....	33

Voltage range.....	33
Common mode voltage range.....	33
Offset voltage range.....	33
Maximum non-destruct differential voltage range.....	33
Reference information.....	34
Specifications.....	34
Common mode rejection ratio graphs.....	35
Maximum differential input voltage vs frequency derating graphs.....	36
Differential input impedance graphs.....	36
TIVP physical specifications.....	37
Probe dimensions.....	38
IsoVu measurement system block diagram.....	39
Connecting the sensor tip cables.....	40
Probe tip tripod.....	40
Installing the probe tip adapters.....	40
Installing the square pins on the circuit board.....	41
User service.....	44
Service offerings.....	44
Warranty repair service.....	44
Calibration and repair service.....	44
Preventive maintenance.....	44
Performance verification procedures.....	44
Required equipment.....	44
Preparation.....	44
System RMS Noise.....	45
Setup the Measurement System.....	45
Perform the measurement.....	45
Test record.....	46
Troubleshooting and error conditions.....	47
Repack the measurement system for shipment.....	48
Remote programming.....	49
Command list.....	49
Index.....	55

List of Figures

Figure 1: TIVP Series IsoVu Measurement System.....	19
Figure 2: Maximum safe handling limits for common mode voltages between the sensor head and earth ground.....	25
Figure 3: RF burn hazard zone around the sensor head.....	25
Figure 4: Connecting the sensor tip cable to the sensor head.....	28
Figure 5: Connect the sensor head to the bipod.....	28
Figure 6: Probe Setup menu.....	31
Figure 7: Typical CMRR values for the sensor tip cables.....	36
Figure 8: Maximum differential input voltage vs. frequency for the sensor tip cables.....	36
Figure 9: Differential input impedance vs. frequency for the sensor tip cables.....	37
Figure 10: Sensor head.....	38
Figure 11: Sensor tip cable.....	38
Figure 12: Compensation box.....	38
Figure 13: Block diagram.....	39
Figure 14: Square pin series sensor tip cables.....	40
Figure 15: Connecting to an adapter on the circuit board with the probe tip tripod.....	40
Figure 16: Lining up the MMCX-to-0.1-inch (2.54 mm) adapter on the circuit board.....	41
Figure 17: Lining up the MMCX-to-0.062-inch (1.57 mm) adapter on the circuit board.....	41
Figure 18: Pushing the MMCX-to-0.062-inch (1.57 mm) adapter in place.....	41
Figure 19: Pushing the MMCX-to-0.1-inch (2.54 mm) adapter in place.....	41
Figure 20: Adapter clearance requirements.....	42
Figure 21: Removing the header from square pins on the circuit board.....	42
Figure 22: Using the soldering aide to install the square pins on the circuit board.....	43

List of Tables

Table 1: Environmental specifications.....	24
Table 2: Ranges and 4/5/6 Series MSO Volts/div settings.....	31
Table 3: Sensor tip cable selection.....	32
Table 4: Physical specifications.....	37
Table 5: Required equipment for performance verification.....	44
Table 6: Test record table.....	46
Table 7: STATUS LED descriptions.....	47
Table 8: SELF CAL LED descriptions.....	47
Table 9: INPUT LED descriptions.....	47
Table 10: ALT Mode LED description.....	47
Table 11: Measurement problems and possible solutions.....	48
Table 12: Probe tip cables and dynamic ranges.....	50

Warranty

Tektronix warrants that this product will be free from defects in materials and workmanship for a period of one (1) year from the date of shipment. If any such product proves defective during this warranty period, Tektronix, at its option, either will repair the defective product without charge for parts and labor, or will provide a replacement in exchange for the defective product. Parts, modules and replacement products used by Tektronix for warranty work may be new or reconditioned to like new performance. All replaced parts, modules and products become the property of Tektronix.

In order to obtain service under this warranty, Customer must notify Tektronix of the defect before the expiration of the warranty period and make suitable arrangements for the performance of service. Customer shall be responsible for packaging and shipping the defective product to the service center designated by Tektronix, with shipping charges prepaid. Tektronix shall pay for the return of the product to Customer if the shipment is to a location within the country in which the Tektronix service center is located. Customer shall be responsible for paying all shipping charges, duties, taxes, and any other charges for products returned to any other locations.

This warranty shall not apply to any defect, failure or damage caused by improper use or improper or inadequate maintenance and care. Tektronix shall not be obligated to furnish service under this warranty a) to repair damage resulting from attempts by personnel other than Tektronix representatives to install, repair or service the product; b) to repair damage resulting from improper use or connection to incompatible equipment; c) to repair any damage or malfunction caused by the use of non-Tektronix supplies; or d) to service a product that has been modified or integrated with other products when the effect of such modification or integration increases the time or difficulty of servicing the product.

THIS WARRANTY IS GIVEN BY TEKTRONIX WITH RESPECT TO THE PRODUCT IN LIEU OF ANY OTHER WARRANTIES, EXPRESS OR IMPLIED. TEKTRONIX AND ITS VENDORS DISCLAIM ANY IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. TEKTRONIX' RESPONSIBILITY TO REPAIR OR REPLACE DEFECTIVE PRODUCTS IS THE SOLE AND EXCLUSIVE REMEDY PROVIDED TO THE CUSTOMER FOR BREACH OF THIS WARRANTY. TEKTRONIX AND ITS VENDORS WILL NOT BE LIABLE FOR ANY INDIRECT, SPECIAL, INCIDENTAL, OR CONSEQUENTIAL DAMAGES IRRESPECTIVE OF WHETHER TEKTRONIX OR THE VENDOR HAS ADVANCE NOTICE OF THE POSSIBILITY OF SUCH DAMAGES.

[W2 – 15AUG04]

TEKTRONIX END USER LICENSE AGREEMENT

This End User Agreement ("Agreement") is an agreement between Tektronix, Inc., an Oregon corporation, and its corporate affiliates, subsidiaries, and divisions as applicable (collectively, "Tektronix," "we," "us," or "our") and You (including any entity or organization you represent, collectively, "Customer" or "You"). Please read this Agreement carefully as this Agreement governs the terms and conditions under which You are permitted to use Tektronix's software and services.

THE SOFTWARE, ENCODED OR INCORPORATED WITHIN EQUIPMENT OR ACCOMPANYING THIS AGREEMENT, IS FURNISHED SUBJECT TO THE TERMS AND CONDITIONS OF THIS AGREEMENT. BY INDICATING YOUR ACCEPTANCE OF THESE TERMS BY SELECTING AN "ACCEPT" OR SIMILAR BUTTON IN A SOFTWARE MENU, OR BY RETAINING THE SOFTWARE FOR MORE THAN THIRTY DAYS OR USING THE SOFTWARE IN ANY MANNER YOU (A) ACCEPT THIS AGREEMENT AND AGREE THAT YOU ARE LEGALLY BOUND BY ITS TERMS; AND (B) REPRESENT AND WARRANT THAT: (I) YOU ARE OF LEGAL AGE TO ENTER INTO A BINDING AGREEMENT; AND (II) IF YOU ARE A REPRESENTATIVE FOR A CORPORATION OR OTHER LEGAL ENTITY, YOU HAVE THE RIGHT, POWER, AND AUTHORITY TO ENTER INTO THIS AGREEMENT ON BEHALF OF SUCH ENTITY AND BIND SUCH ENTITY TO ITS TERMS. IF YOU DO NOT AGREE TO THE TERMS OF THIS AGREEMENT, TEKTRONIX WILL NOT AND DOES NOT LICENSE THE SOFTWARE TO YOU AND YOU MUST NOT DOWNLOAD, INSTALL, OR USE THE SOFTWARE. UNITED STATES GOVERNMENT CUSTOMERS OR END-USERS MAY REQUEST A GOVERNMENT ADDENDUM TO THIS AGREEMENT.

NOTWITHSTANDING ANYTHING TO THE CONTRARY IN THIS AGREEMENT OR YOUR ACCEPTANCE OF THE TERMS AND CONDITIONS OF THIS AGREEMENT, NO LICENSE IS GRANTED (WHETHER EXPRESSLY, BY IMPLICATION, OR OTHERWISE) UNDER THIS AGREEMENT TO ANY SOFTWARE THAT YOU DID NOT ACQUIRE LAWFULLY OR THAT IS NOT A LEGITIMATE, AUTHORIZED COPY OF TEKTRONIX'S SOFTWARE. THIS AGREEMENT EXPRESSLY EXCLUDES ANY RIGHTS CONCERNING SUCH ILLEGITIMATE COPIES.

IF THESE TERMS ARE NOT ACCEPTABLE, THE UNUSED SOFTWARE AND ANY ACCOMPANYING DOCUMENTATION SHOULD BE RETURNED PROMPTLY TO TEKTRONIX (WITHIN 30 DAYS OF PURCHASE) FOR A FULL REFUND OF THE LICENSE FEE PAID. (FOR INFORMATION REGARDING THE RETURN OF SOFTWARE ENCODED OR INCORPORATED WITHIN EQUIPMENT, CONTACT THE NEAREST TEKTRONIX SALES OFFICE.)

DEFINITIONS

"Equipment" means Tektronix equipment that the Software is encoded or incorporated within or installed onto.

LICENSE

Subject to the terms and conditions of this Agreement, Tektronix grants You a non-exclusive, non-transferable license to the Software, as follows

You may:

1. Use the Software with the Equipment, or if the Software is not encoded or incorporated in any Tektronix equipment, on no more than one machine at a time; and
2. Copy the Software for archival or backup purposes, provided that no more than one (1) such copy is permitted to exist at any one time, and provided that each copy includes a reproduction of any patent or copyright notice or restrictive rights legend that was included with the Software, as received from Tektronix;
3. Fully transfer the Equipment to a third party but only if prominently accompanied by this End User License Agreement, and such third-party recipients agree to be bound by the terms of this Agreement; and
4. Integrate Tektronix products that contain the Software into a system and sell or distribute that system to third parties, provided that those third parties are bound by the terms of this Agreement, and provided that You (i) do not separate the Software from any Equipment it is incorporated into, (ii) do not retain any copies of the Software, and (iii) do not modify the Software.

You may not:

1. Use the Software other than for its intended purpose as provided above in the section "You may," or in conflict with the terms and restrictions of this Agreement;
2. Distribute or transfer the Software to any person or organization outside of Your organization without Tektronix's prior written consent, except in connection with a permitted use authorized in "You may" paragraphs 3 or 4 above;

3. Decompile, decrypt, disassemble, or otherwise attempt to derive the source code, techniques, processes, algorithms, know-how, or other information (collectively "Reverse Engineer") from the Software or permit or induce any third party to do so, except to the limited extent allowed by directly applicable law or third party license (if any), and only to obtain information necessary to achieve interoperability of independently created software with the Software;
4. Modify, translate, adapt, or create derivative works of the Software, or merge the Software with any other software;
5. Copy the documentation accompanying the Software;
6. Remove any copyright, trademark, or other proprietary notices from the Software or any media relating thereto; or
7. Export or re-export, directly or indirectly, the Software or Equipment, any associated documentation, or systems created in accordance with "You may" section 4 above, to any country to which such export or re-export is restricted by law or regulation of the United States or any foreign government having jurisdiction without the prior authorization, if required, of the Office of Export Administration, Department of Commerce, Washington, D.C. and the corresponding agency of such foreign government;
8. Use the Software or Equipment in any manner or for any purpose that infringes, misappropriates, or otherwise violates any intellectual property rights or other proprietary rights of any person, or any applicable laws;
9. Use the Software or Equipment in a network or system with other products or services that are incompatible, insecure or not compliant with applicable laws;
10. Bypass, circumvent, damage or otherwise interfere with any security or other features of the Software or Equipment designed to control the manner in which they are used, or harvest or mine Tektronix's proprietary content or information from the Software or Equipment.

THE SOFTWARE MAY NOT BE USED, COPIED, MODIFIED, MERGED, OR TRANSFERRED TO ANOTHER EXCEPT AS EXPRESSLY PERMITTED BY THESE TERMS AND CONDITIONS.

FEEDBACK

If You provide feedback to Tektronix concerning the functionality and performance of the Software or Equipment, including without limitation identifying potential errors and improvements, any comments, questions, suggestions, or the like ("Feedback"), Tektronix is free to use such Feedback without any attribution, compensation, or restriction in any manner to improve or enhance its products, irrespective of any other obligation or limitation between the Parties governing such Feedback. You hereby grant Tektronix an irrevocable, worldwide, perpetual, royalty-free license to use Your Feedback for any purpose whatsoever and waive any moral rights You may have in the Feedback. Tektronix is not obligated to use Your Feedback.

OWNERSHIP

Title to the Software and all copies thereof, but not the media on which the Software or copies may reside, shall remain with Tektronix or others from whom Tektronix has obtained a respective licensing right.

GOVERNMENT NOTICE

If the Software or any related documentation is acquired by or for an agency of the U.S. Government, the Software and documentation shall be considered "commercial computer software" or "commercial computer software documentation" respectively, as those terms are used in 48 CFR §12.212, 48 CFR §227.7202, or 48 CFR §252.227-7014, and are licensed with only those rights as are granted to all other licensees as set forth in this Agreement.

TERM

The license granted herein is effective until terminated. The license may be terminated by You at any time upon written notice to Tektronix. The license may be terminated by Tektronix if You fail to comply with any term or condition and such failure is not remedied within fifteen (15) days after notice hereof from Tektronix. Upon termination by either party, You shall return to Tektronix or destroy, the Software and all associated documentation, together with all copies in any form.

IF YOU TRANSFER, DISTRIBUTE, OR OTHERWISE MAKE AVAILABLE ANY COPY, MODIFICATION, OR MERGED PORTION OF THE SOFTWARE WITHOUT THE AS EXPRESS PERMISSION OF THESE TERMS AND CONDITIONS OR PRIOR WRITTEN CONSENT OF TEKTRONIX, YOUR LICENSE WILL BE IMMEDIATELY AND AUTOMATICALLY TERMINATED.

LIMITED WARRANTY

Tektronix does not warrant that the functions contained in the Software will meet Your requirements or that the operation of the Software will be uninterrupted, secure, or error-free.

EXCEPT AS SEPARATELY PROVIDED IN A WRITTEN WARRANTY FROM TEKTRONIX, THE SOFTWARE IS PROVIDED "AS IS" WITHOUT ANY WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO, THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, TITLE, QUIET ENJOYMENT, AND NON-INFRINGEMENT.

THE SOFTWARE IS NOT DESIGNED OR INTENDED FOR USE IN HAZARDOUS ENVIRONMENTS REQUIRING FAIL-SAFE PERFORMANCE INCLUDING WITHOUT LIMITATION, IN THE OPERATION OF NUCLEAR FACILITIES, AIRCRAFT NAVIGATION OR COMMUNICATION SYSTEMS, AIR TRAFFIC CONTROL, WEAPONS SYSTEMS, DIRECT LIFE-SUPPORT MACHINES, OR ANY OTHER APPLICATION IN WHICH THE FAILURE OF THE SOFTWARE COULD LEAD TO DEATH, PERSONAL INJURY OR SEVERE PHYSICAL OR PROPERTY DAMAGE (COLLECTIVELY "HAZARDOUS ACTIVITIES"). TEKTRONIX AND ITS AFFILIATES, LICENSORS, AND RESELLERS EXPRESSLY DISCLAIM ANY EXPRESS OR IMPLIED WARRANTY OF FITNESS FOR HAZARDOUS ACTIVITIES.

LIMITATION OF LIABILITY

IN NO EVENT SHALL TEKTRONIX, ITS AFFILIATES, LICENSORS, OR RESELLERS BE LIABLE FOR: (1) ECONOMICAL, INCIDENTAL, CONSEQUENTIAL, INDIRECT, SPECIAL, PUNITIVE OR EXEMPLARY DAMAGES, WHETHER CLAIMED UNDER CONTRACT, TORT OR ANY OTHER LEGAL THEORY, (2) LOSS OF OR DAMAGE TO YOUR DATA OR PROGRAMMING, LOSS OF PROFITS, BUSINESS INTERRUPTION, OR OTHER PECUNIARY LOSS ARISING FROM THE USE OF (OR INABILITY TO USE) THE SOFTWARE, (3) PENALTIES OR PENALTY CLAUSES OF ANY DESCRIPTION, (4) ANY DAMAGE, CLAIMS, OR LOSSES RESULTING FROM THE USE OF THE SOFTWARE IN CONJUNCTION WITH OTHER PRODUCTS OR SERVICES (INCLUDING THIRD-PARTY PRODUCTS OR SERVICES); OR (5) INDEMNIFICATION OF YOU OR OTHERS FOR COSTS, DAMAGES, OR EXPENSES RELATED TO THE GOODS OR SERVICES PROVIDED UNDER THIS LIMITED WARRANTY, EVEN IF TEKTRONIX OR ITS AFFILIATES, LICENSORS, OR RESELLERS HAVE ADVANCE NOTICE OF THE POSSIBILITY OF SUCH DAMAGES. BECAUSE SOME STATES/ JURISDICTIONS DO NOT ALLOW THE EXCLUSION OR LIMITATION OF LIABILITY FOR CONSEQUENTIAL OR INCIDENTAL DAMAGES, SOME OF THE ABOVE LIMITATIONS MAY NOT APPLY TO YOU, BUT THEY SHALL APPLY TO THE MAXIMUM EXTENT PERMITTED BY LAW. NOTWITHSTANDING ANYTHING HEREIN TO THE CONTRARY, IN NO EVENT SHALL TEKTRONIX'S TOTAL AGGREGATED LIABILITY TO YOU FOR ALL DAMAGES IN ANY ONE OR MORE CAUSES OF ACTION EXCEED THE AMOUNT RECEIVED BY TEKTRONIX FROM YOU FOR THE SOFTWARE OR EQUIPMENT.

You are solely responsible for Your data. You must back up Your data before Tektronix or a third party performs any remedial, upgrade, or other work on Your systems, including any Equipment. If applicable law prohibits exclusion of liability for lost data, then Tektronix will only be liable for the cost of the typical effort to recover the lost data from Your last available back up.

SECURITY DISCLAIMER

This Software and its associated Equipment are not designed or intended to be used with unsecure networks. You acknowledge that use of the Equipment may rely upon certain networks, systems, and data communication mediums that are not controlled by Tektronix and that may be vulnerable to data or security breaches, including, without limitation, internet networks used by Your internet providers and the databases and servers controlled by Your internet providers. Tektronix shall not be liable for any such breaches, including without limitation, damages and/or loss of data related to any security breach, and disclaims all warranties, including any implied or express warranties that any content will be secure or not otherwise lost or altered.

For the avoidance of doubt, if You choose to connect this Software or Equipment to a network, it is Your sole responsibility to provide and continuously ensure a secure connection to that network. You agree to establish and maintain appropriate measures (e.g., firewalls, authentication measures, encryption, anti-virus applications, etc.) to protect the Software and Equipment and any associated data against security breaches including unauthorized access, destruction, use, modification, or disclosure.

Notwithstanding the foregoing, You shall not use any Products in a network with other products or services that are incompatible, insecure or not compliant with applicable laws.

THIRD-PARTY DISCLAIMER

The Software may contain software owned by third parties and obtained under a license from those parties ("Third Party Software"). Your use of such Third Party Software is subject to the terms and conditions of this Agreement and the applicable Third Party Software licenses. Except as expressly agreed otherwise, third parties do not warrant the Third Party Software, do not assume any liability with respect to its use, and do not undertake to furnish any support or information relating thereto.

GENERAL

Unless the Customer is the United States Government, this Agreement contains the entire agreement between the parties with respect to the use, reproduction, and transfer of the Software, and shall be governed by the laws of the state of Oregon.

You shall be responsible for any taxes that may now or hereafter be imposed, levied or assessed with respect to the possession or use of the Software or the rights and licenses granted under this Agreement, including any sales, use, property, value added, and excise taxes, and similar taxes, duties, or charges.

Any waiver by either party of any provision of this Agreement shall not constitute or be deemed a subsequent waiver of that or any other portion.

You may not assign this Agreement or any right or obligation under this Agreement, or delegate any performance, without Tektronix's prior written consent. This section does not prohibit You from transferring the Equipment in accordance with Subsections 3 and 4 of the Section titled "You may" above.

All questions regarding this Agreement should be directed to the nearest Tektronix Sales Office.

Third Party Software Licenses

Freescal Kinetic Design Studio

This component module is generated by Processor Expert. Do not modify it.

Copyright : 1997 - 2015 Freescale Semiconductor, Inc.

All Rights Reserved.

Redistribution and use in source and binary forms, with or without modification, are permitted provided that the following conditions are met:

- Redistributions of source code must retain the above copyright notice, this list of conditions and the following disclaimer.
- Redistributions in binary form must reproduce the above copyright notice, this list of conditions and the following disclaimer in the documentation and/or other materials provided with the distribution.
- Neither the name of Freescale Semiconductor, Inc. nor the names of its contributors may be used to endorse or promote products derived from this software without specific prior written permission.

THIS SOFTWARE IS PROVIDED BY THE COPYRIGHT HOLDERS AND CONTRIBUTORS "AS IS" AND ANY EXPRESS OR IMPLIED WARRANTIES, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE ARE DISCLAIMED. IN NO EVENT SHALL THE COPYRIGHT HOLDER OR CONTRIBUTORS BE LIABLE FOR ANY DIRECT, INDIRECT, INCIDENTAL, SPECIAL, EXEMPLARY, OR CONSEQUENTIAL DAMAGES (INCLUDING, BUT NOT LIMITED TO, PROCUREMENT OF SUBSTITUTE GOODS OR SERVICES; LOSS OF USE, DATA, OR PROFITS; OR BUSINESS INTERRUPTION) HOWEVER CAUSED AND ON ANY THEORY OF LIABILITY, WHETHER IN CONTRACT, STRICT LIABILITY, OR TORT (INCLUDING NEGLIGENCE OR OTHERWISE) ARISING IN ANY WAY OUT OF THE USE OF THIS SOFTWARE, EVEN IF ADVISED OF THE POSSIBILITY OF SUCH DAMAGE.

[http: www.freescale.com](http://www.freescale.com)

[mail: support@freescale.com](mailto:support@freescale.com)

IAR Embedded Workbench for ARM

IARSourceLicense.txt Version 1.0

The following license agreement applies to linker command files, example projects unless another license is explicitly stated, the cstartup code, low_level_init.c, and some other low-level runtime library files.

Copyright 2012, IAR Systems AB.

This source code is the property of IAR Systems. The source code may only be used together with the IAR Embedded Workbench. Redistribution and use in source and binary forms, with or without modification, is permitted provided that the following conditions are met:

- Redistributions of source code, in whole or in part, must retain the above copyright notice, this list of conditions and the disclaimer below.
- IAR Systems name may not be used to endorse or promote products derived from this software without specific prior written permission.

THE SOFTWARE IS PROVIDED "AS IS" AND THE AUTHOR DISCLAIMS ALL WARRANTIES WITH REGARD TO THIS SOFTWARE INCLUDING ALL IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS. IN NO EVENT SHALL THE AUTHOR BE LIABLE FOR ANY SPECIAL, DIRECT, INDIRECT, OR CONSEQUENTIAL DAMAGES OR ANY DAMAGES WHATSOEVER RESULTING FROM LOSS OF USE, DATA OR PROFITS, WHETHER IN AN ACTION OF CONTRACT, NEGLIGENCE OR OTHER TORTIOUS ACTION, ARISING OUT OF OR IN CONNECTION WITH THE USE OR PERFORMANCE OF THIS SOFTWARE.

Iowegian ScopellIR

Name: Biquad.c

Name: Biquad.h

Description: Provides a template for implementing IIR filters as a cascade of second-order sections, aka, "biquads".

by Grant R. Griffin

Copyright 2007-2015, Iowegian International Corporation

(<http://www.iowegian.com>)

The Wide Open License (WOL)

Permission to use, copy, modify, distribute and sell this software and its documentation for any purpose is hereby granted without fee, provided that the above copyright notice and this license appear in all source copies.

THIS SOFTWARE IS PROVIDED "AS IS" WITHOUT EXPRESS OR IMPLIED WARRANTY OF ANY KIND. See <http://www.dspguru.com/wide-open-license> for more information.

Important safety information

This manual contains information and warnings that must be followed by the user for safe operation and to keep the product in a safe condition.

To safely perform service on this product, see the *Service safety summary* that follows the *General safety summary*.

General safety summary

Use the product only as specified. Review the following safety precautions to avoid injury and prevent damage to this product or any products connected to it. Carefully read all instructions. Retain these instructions for future reference.

The product is designed to be used by trained personnel only.

Before use, always check the product with a known source to be sure it is operating correctly.

To avoid fire or personal injury

Connect and disconnect properly

Do not connect or disconnect sensor tip cables, test leads, or accessories while they are connected to a voltage source. Use only test leads and accessories supplied with the product, or indicated by Tektronix to be suitable for the product.

Use only insulated voltage probes, test leads, and adapters supplied with the product, or indicated by Tektronix to be suitable for the product.

Observe all terminal ratings

To avoid fire or shock hazard, observe all rating and markings on the product. Consult the product manual for further ratings information before making connections to the product.

Do not exceed the Measurement Category (CAT) rating and voltage or current rating of the rated individual component of a product or accessory. Do not apply a potential lowest that exceeds the maximum rating.

The measuring terminals on this product are not rated for connection to mains or Category II, III, or IV circuits.

Do not operate without covers.

Do not operate this product with covers or panels removed, or with the case open. Hazardous voltage exposure is possible.

Avoid exposed circuitry

Do not touch exposed connections and components when power is present.

Do not operate with suspected failures

If you suspect that there is damage to this product, have it inspected by qualified service personnel.

Disable the product if it is damaged.

Do not operate in wet/damp conditions

Do not operate in an explosive atmosphere

Keep product surfaces clean and dry

Clean with dry cloth only

Sensor tip cables

Maintain safe clearance from the sensor head and sensor tip cable while connected to the energized circuit as recommended in this manual.

Remove the sensor tip cable and adapters from the test circuit when not in use.

Leave the sensor tip cable connected to the sensor head when not in use.

Use only correct Measurement Category (CAT), voltage, temperature, altitude, and amperage rated sensor tip cables and accessories for any measurement.

Beware of high voltages

Understand the voltage ratings for the product you are using and do not exceed those ratings. It is important to know and understand the maximum measurement voltage rating of the product. The voltage rating depends on the measurement category, the instrument, and your application. Refer to the Specifications section of the manual for more information.



Warning: To prevent electrical shock, do not exceed the maximum measurement or maximum voltage category.

Connect and disconnect properly



CAUTION: To avoid damage to the equipment, de-energize the test circuit before connecting or disconnecting the sensor tip cable.

Terms in this manual

These terms may appear in this manual:



Warning: Warning statements identify conditions or practices that could result in injury or loss of life.



CAUTION: Caution statements identify conditions or practices that could result in damage to this product or other property.

Isolated, electrically floating

The terms *isolated*, *electrically floating*, and *galvanically isolated* are used in this document to indicate a measurement where there is no direct conduction path to earth ground.

Symbols and terms on the product

These terms may appear on the product:

- DANGER indicates an injury hazard immediately accessible as you read the marking.
- WARNING indicates an injury hazard not immediately accessible as you read the marking.
- CAUTION indicates a hazard to property including the product.



When this symbol is marked on the product, be sure to consult the manual to find out the nature of the potential hazards and any actions which have to be taken to avoid them. (This symbol may also be used to refer the user to ratings in the manual.)



CAUTION
Refer to Manual



WARNING
High Voltage

Compliance information

This section lists the Safety and Environmental standards with which the instrument complies. This product is intended for use by professionals and trained personnel only; it is not designed for use in households or by children.

Safety compliance

This section lists the safety standards with which the product complies and other safety compliance information.

EU declaration of conformity – low voltage

Compliance was demonstrated to the following specification as listed in the Official Journal of the European Union:

Low Voltage Directive 2014/35/EU.

- EN 61010-1. Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use – Part 1: General Requirements

U.S. nationally recognized testing laboratory listing

- UL 61010-1. Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use – Part 1: General Requirements

Canadian certification

- CAN/CSA-C22.2 No. 61010-1. Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use – Part 1: General Requirements

Additional compliances

- IEC 61010-1. Safety Requirements for Electrical Equipment for Measurement, Control, and Laboratory Use – Part 1: General Requirements
- EN 60825-1. Safety of Laser Products-Part 1: Equipment Classification and Requirements - Edition 3 (2014)
- US 21CFR PT1010 Performance Standard for Electronic Parts 2015
- US 21CFR PT1040 Performance Standards for Light Emitting Products 2015

Equipment type

Test and measuring equipment.

CLASS 1 LASER PRODUCT.

Pollution degree description

A measure of the contaminants that could occur in the environment around and within a product. Typically the internal environment inside a product is considered to be the same as the external. Products should be used only in the environment for which they are rated.

- Pollution Degree 1. No pollution or only dry, nonconductive pollution occurs. Products in this category are generally encapsulated, hermetically sealed, or located in clean rooms.
- Pollution Degree 2. Normally only dry, nonconductive pollution occurs. Occasionally a temporary conductivity that is caused by condensation must be expected. This location is a typical office/home environment. Temporary condensation occurs only when the product is out of service.
- Pollution Degree 3. Conductive pollution, or dry, nonconductive pollution that becomes conductive due to condensation. These are sheltered locations where neither temperature nor humidity is controlled. The area is protected from direct sunshine, rain, or direct wind.
- Pollution Degree 4. Pollution that generates persistent conductivity through conductive dust, rain, or snow. Typical outdoor locations.

Pollution degree rating

Pollution degree 2 (as defined in IEC 61010-1). Rated for indoor, dry location use only.

IP rating

IP20 (as defined in IEC 60529).

Measurement and overvoltage category descriptions

Measurement terminals on this product may be rated for measuring mains voltages from one or more of the following categories (see specific ratings marked on the product and in the manual).

- Category I. Circuits not directly connected to a mains supply.
- Category II. Circuits directly connected to the building wiring at utilization points (socket outlets and similar points).
- Category III. In the building wiring and distribution system.
- Category IV. At the source of the electrical supply to the building.



Note: Only measurement circuits have a measurement category rating. Other circuits within the product do not have either rating.

Environmental considerations

This section provides information about the environmental impact of the product.

Product end-of-life handling

Observe the following guidelines when recycling an instrument or component:

Equipment recycling. Production of this equipment required the extraction and use of natural resources. The equipment may contain substances that could be harmful to the environment or human health if improperly handled at the product's end of life. To avoid release of such substances into the environment and to reduce the use of natural resources, we encourage you to recycle this product in an appropriate system that will ensure that most of the materials are reused or recycled appropriately.



This symbol indicates that this product complies with the applicable European Union requirements according to Directives 2012/19/EU and 2006/66/EC on waste electrical and electronic equipment (WEEE) and batteries. For information about recycling options, check the Tektronix Web site (www.tek.com/productrecycling).

Preface

This document provides information for installing and using the Tektronix TIVP IsoVu® Generation 2 Isolated Probe. The probe offers a galvanically isolated measurement solution for accurately resolving high bandwidth, high voltage differential signals in the presence of large common mode voltages with the best in class common mode rejection performance across its bandwidth.

Key features

- New IsoVu technology - galvanically isolated, floating measurement system
 - Bandwidth from DC to 1 GHz
 - Up to 160 dB (100 million to 1 common mode rejection ratio) at DC, 140 dB (10 million to 1) at 1 MHz, 120 dB (1 million to 1) at 100 MHz, and 80 dB (10,000 to 1) at 1 GHz
- Differential voltages up to ± 2500 Vpk (sensor tip cable dependent)
- Large common mode voltage range up to 60 kV peak
- High impedance input up to 40 M Ω (sensor tip cable dependent)
- Large input offset range up to ± 2500 Vpk (sensor tip cable dependent)
- DC and AC input coupling

Laser certification

CLASS 1 LASER PRODUCT

This product complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.



CAUTION: Use of controls or adjustments for performance of procedures other than those specified herein may result in hazardous radiation exposure.

Product description

The Tektronix IsoVu® (TIVP) Generation 2 is a completely galvanically isolated probe tip cable, sensor head, and TekVPI interface as shown in the following figure. Hazardous voltages in the sensor head are completely isolated from the oscilloscope by optical fiber cables.

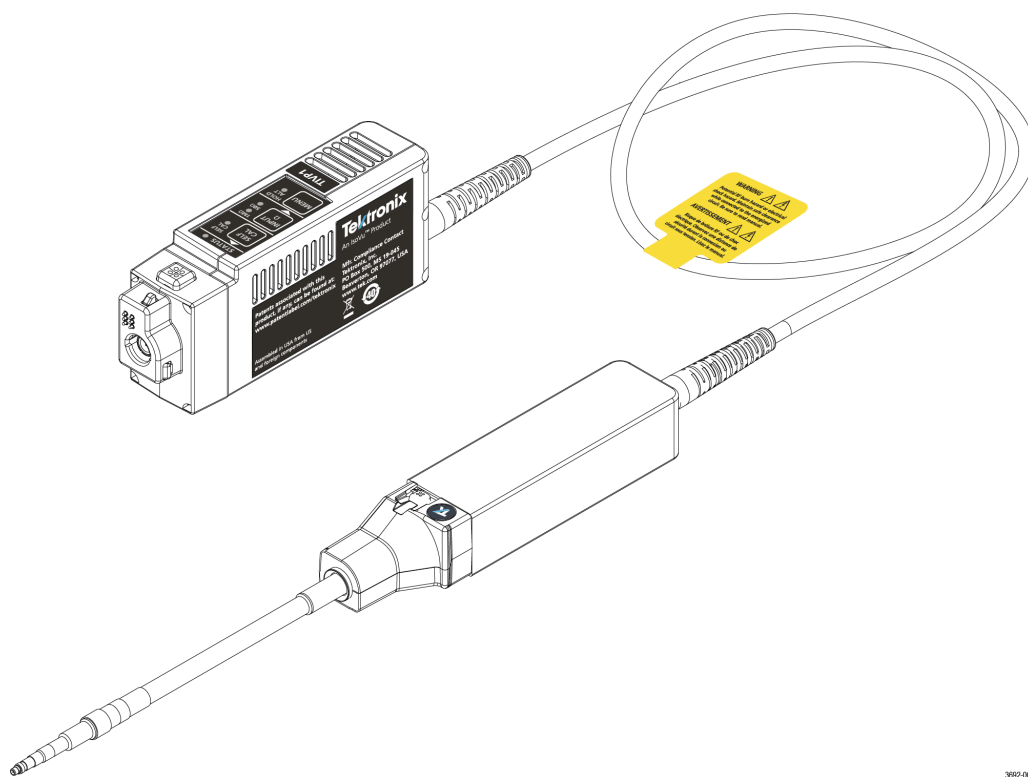


Figure 1: TIVP Series IsoVu Measurement System

Compensation box

The TekVPI compensation box (comp box) connects the measurement system to one of the input channels on the oscilloscope. Power is supplied to the measurement system through the TekVPI interface of the oscilloscope. The buttons and indicators on the comp box provide a means for controlling the probe and indicating the overall status.

Sensor head

The sensor head provides an interface between the device-under-test (DUT) and the compensation box. It contains an electro-optic converter that converts the electrical signal from the sensor tip cables to an optical signal sent to the comp box.

Sensor tip cables

Several sensor tip cables options are available to connect the sensor head to the DUT:

- TIVPMX10X, 10X MMCX tip cable connector
- TIVPMX50X, 50X MMCX tip cable connector
- TIVPSQ100X, 100X 0.1-inch (2.54 mm) square pin connector
- TIVPWS500X, 500X 0.2-inch (5.08 mm) square pin connector
- TIVPMX1X, 1X MMCX tip cable connector

Models

The TIVP Series IsoVu Measurement System includes the following models:

- TIVP1. Tektronix IsoVu® Generation 2; 1 GHz Isolated Probe
- TIVP05. Tektronix IsoVu® Generation 2; 500 MHz Isolated Probe
- TIVP02. Tektronix IsoVu® Generation 2; 200 MHz Isolated Probe
- TIVP1L. Tektronix IsoVu® Generation 2; 1 GHz Isolated probe (10 m cable)
- TIVP05L. Tektronix IsoVu® Generation 2; 500 MHz Isolated probe (10 m cable)
- TIVP02L. Tektronix IsoVu® Generation 2; 200 MHz Isolated probe (10 m cable)

Supported oscilloscopes

The measurement system can be used with the 4, 5, and 6 Series Mixed Signal Oscilloscopes with oscilloscope software version 1.28 or greater. For all other oscilloscopes, contact your local Tektronix representative.

Accessories

This section lists the standard and optional accessories available for the measurement system.

Standard accessories

The following table list the accessories that are shipped with the probe.

Accessory	Description	Part number
	The 10X MMCX Tip is included in every TIVP. The MMCX tip is recommended for the best bandwidth and CMRR performance. 0.100" Square Pin and 0.200" Wide Square Pin tips are available as optional accessories.	TIVPMX10X
	The Bipod is used to hold the probe. TIVP can rotate in the holder to accommodate square pin headers.	352-1179-xx
	The Probe Tip Adapter is used to adapt an MMCX IsoVu tip to standard 0.100" spaced, 0.025" square pins.	131-9717-xx
	The SMA Wrench/Driver Tool is a 5/16" wrench for use on a SMA connector.	003-1947-xx

Table continued...

Accessory	Description	Part number
	The Carrying Case is a soft case (with foam insert) that protects the TIVP and enforces the optical fiber minimum bend radius.	016-2147-xx
	10 m version	016-2149-xx

Optional accessories

The following table lists optional accessories, such as other sensor tip cables are available.

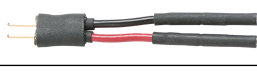
Accessory	Description	Part number
	50X MMCX sensor tip cable	TIVPMX50X
	100X sensor tip cable with 0.100" spaced square pin connector	TIVPSQ100X
	500X sensor tip cable with 0.200" spaced wide square pin connector	TIVPWS500X
	1X MMCX sensor tip cable	TIVPMX1X
	Square Pin to MMCX Adapter, 0.062" Spacing	131-9677-xx
	Probe Tip Tripod Support	352-1170-xx
	Lead, MMCX to IC Grabber	196-3546-xx
	Lead, Square Pin to IC Grabber	196-3547-xx
	Lead, Wide Square Pin to Banana Jack	020-3189-xx
	Square Pin Y-lead	196-3434-xx
	MicroCKT grabbers	206-0569-xx

Table continued...

Accessory	Description	Part number
	Spare Pins for 0.062" Spaced Test Points	020-3169-xx
	Solder Aid for 0.062" Spaced Square Pins	003-1946-xx

Getting started

Learn about the controls, indicators, and the basic operations of the probe.

Operating considerations

Read this section before installing your measurement system to be aware of the operating requirements and clearance requirements including possible hazardous areas when the measurement system is connected to the DUT.

Measurement system handling best practices

The measurement system consists of quality parts and should be treated with care to avoid damage or degrading the performance due to mishandling. Consider the following precautions when handling the fiber-optic cables and sensor tip cables.

- Do not crush, crimp, or sharply bend the fiber-optic cable. Avoid making loops in the fiber-optic cable smaller than 5 inches (12.7 cm).
- Do not twist the fiber-optic cable; twisting the cable will stress the optical fibers.
- Do not allow kinks or knots to develop in the fiber-optic cable.
- Avoid putting tension on the fiber-optic cable.
- Do not pull or jerk the fiber-optic cable, especially when kinks or knots are present.
- Do not drop the sensor head or comp box assembly since damage and misalignment of the internal optical components can result.
- Avoid over-bending the sensor tip cables; do not exceed the minimum bend radius of 2.0 inches (5.1 cm).
- Avoid crushing the cables by accidentally running over the cable with a chair wheel or by dropping a heavy object onto the cable.
- Never support the weight of the sensor head or comp box by the fiber-optic cable.
- Store the measurement system in the supplied carrying case when not in use.

Environmental requirements

The maximum operating environmental ratings for the measurement system when connected to a DUT and a Tektronix oscilloscope.

Table 1: Environmental specifications

Feature		Description
Temperature	Operating	Comp box: 0° C to 30° C Probe head: 0° C to 50° C Tip Cable/Adapters: -40° C to 85° C
	Non-Operating	Comp box: -20° C to +70° C Probe head: -20° C to +70° C Tip Cable/Adapters: -40° C to 85° C
Humidity	Operating	Comp box: 5% to 85% RH (Relative Humidity) at up to +30° C, non-condensing Probe head: 5% to 85% RH (Relative Humidity) at up to +40° C, 5% to 45% RH above +40° C up to +50° C, non-condensing. Tip Cable/Adapters: 5% to 85% RH (Relative Humidity) at up to +85° C, non-condensing
	Non-Operating	Comp Box/Probe Head: 5% to 85% RH (Relative Humidity) at up to +40° C, 5% to 45% RH above +40° C up to +85° C, non-condensing. Tip Cable/Adapters: 5% to 85% RH (Relative Humidity) at up to +85° C, non-condensing.
Altitude	Operating	3000 m (9843 ft.)
	Non-Operating	12,000 m (39370 ft.)

Clearance requirements

The unique common mode voltage range of the measurement system allows it to be used in the presence of high frequency/high voltage common mode signals. It is important to observe all precautions while using this product.



Warning: Electrical shock can occur while using this measurement system. The system is intended to isolate the operator from hazardous input voltages (common voltages); the plastic case of the sensor head and the shield on the sensor tip cable do not supply safe isolation. Maintain the safe clearance from the sensor head and sensor tip cable while the measurement system is connected to the energized circuit as recommended in this document. Do not access the RF Burn Hazard Zone while taking measurements on a live circuit.

While measuring high frequency common mode signals, there is a risk of RF burns. Refer to the following derating curve to identify the danger areas. Measuring common mode signals within the gray shaded area can result in RF burns within 1 m (40 in.) of the sensor head and earth ground.

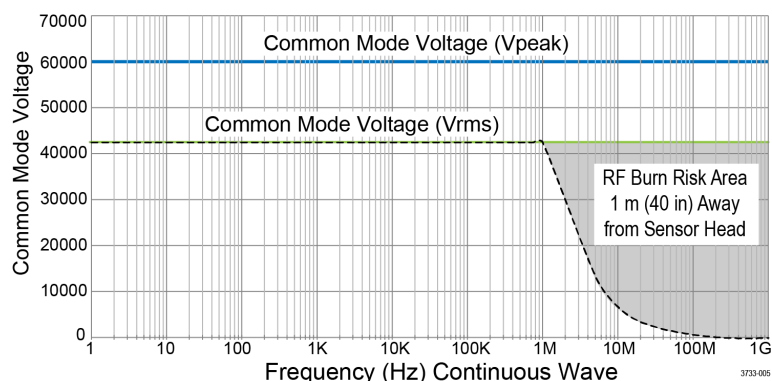


Figure 2: Maximum safe handling limits for common mode voltages between the sensor head and earth ground.

The following figure shows the components of the measurement system and the potential RF burn area when working with hazardous voltages. The RF burn area of 1 m (40 in.) is indicated by the dashed lines surrounding the sensor head.

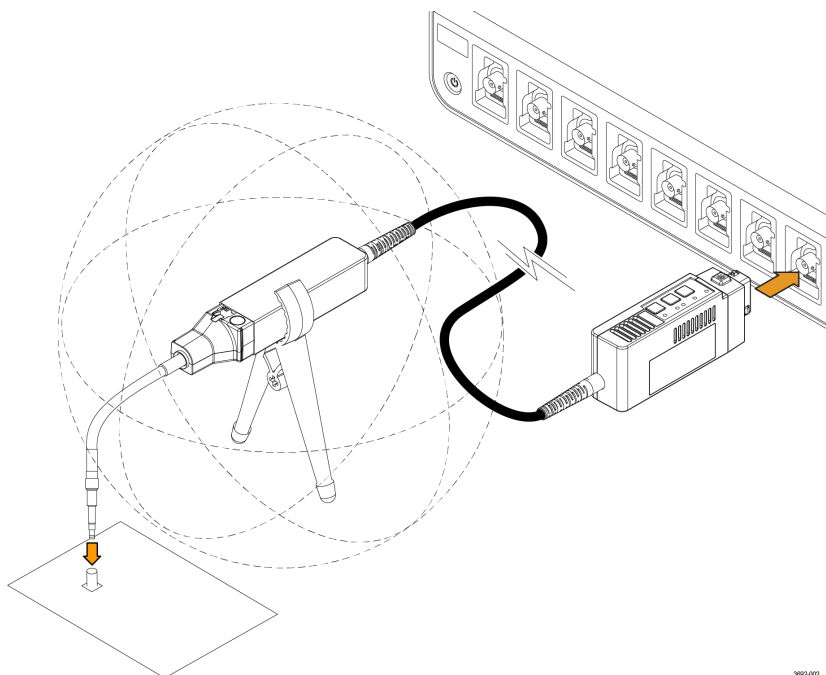
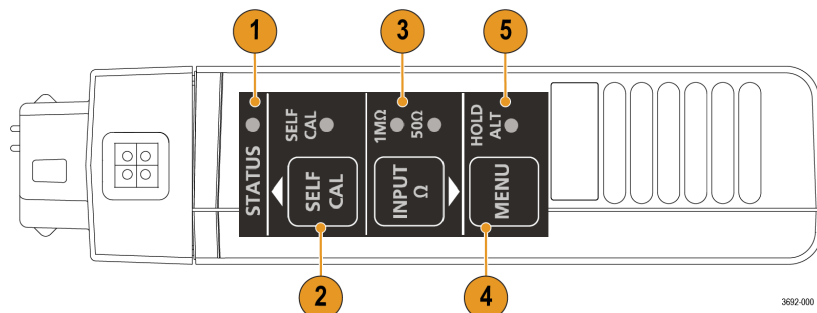


Figure 3: RF burn hazard zone around the sensor head

Controls and indicators

A description of the controls and indicators on the compensation box.



1. **STATUS** indicator. For more information on the state of the LED, see [Table 7: STATUS LED descriptions](#) on page 47
2. **SELF CAL** button and LED indicator: Press to start self-calibration routine. For more information on the state of the LED, see [Table 8: SELF CAL LED descriptions](#) on page 47
3. **INPUT** Termination button and LED indicator: With no tip attached, press to toggle the sensor head between 50 Ω and 1 M Ω termination. For more information on the state of the LED, see [Table 9: INPUT LED descriptions](#) on page 47
4. **MENU** button: Press to open the Probe Vertical menu on the oscilloscope.
5. **ALT** mode indicator: Displays special information about the probe. For more information, see [Table 10: ALT Mode LED description](#) on page 47

Cable flags

Flags on the cable provide high-level specifications for connecting to the DUT. They also provide a potential RF burn hazards warning and a self-calibration notification.



Sensor tip cable

Each sensor tip cable has a label that provides the maximum dynamic range and displays the attenuation factor.

TIVPMX1X $\pm 5V$

TIVPMX10X $\pm 50V$

TIVPMX50X $\pm 250V$

TIVPSQ100X $\pm 500V$

TIVPWS500X $\pm 2.5kV$

Connecting to a circuit



Warning: This measurement system contains laser sources; exposing these laser sources may cause laser exposure. Except for the sensor tip cables on the sensor head, do not remove any plastic or metallic covers from the sensor head or comp box or attempt to disassemble the product.



Warning: Do not connect the measurement system to an energized circuit to avoid the risk of shock. Always de-energize the circuit-under-test before installing or removing the tip cable from the circuit-under-test. The plastic case of the sensor head and the shield tip of the sensor cable do not supply the isolation.



Warning: To avoid the risk of electrical shock or RF burns while the DUT is energized, do not touch the sensor head or sensor tip cable while taking measurements. Always keep a 1 m (40 in.) clearance from the sensor head during the measurement. [Figure 3: RF burn hazard zone around the sensor head](#) on page 25

Be sure to check the maximum ratings and derating curve for more information on the RF burn hazard zone. [Figure 2: Maximum safe handling limits for common mode voltages between the sensor head and earth ground.](#) on page 25



CAUTION: To avoid possible damage to the equipment, do not connect the coaxial (common) shield of the sensor tip cable or SMA input to the high impedance portion of a circuit. The additional capacitance can cause circuit damage. Connect the coaxial (common) shield to the low impedance section of the circuit.



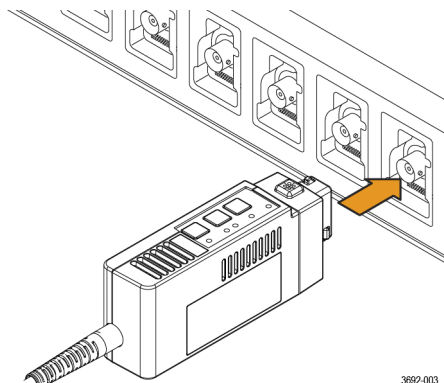
Note: Touching the sensor head or sensor tip cable when measuring a high frequency common mode signal increases the capacitive coupling and can degrade the common mode loading on the circuit-under-test.



Warning: To prevent the arc flash caused by a different potential, do not place the sensor head or sensor tip cable on the circuit that has the different voltage.

The following steps describe the process for connecting the measurement system between an oscilloscope and the DUT.

1. Verify the DUT is not connected to an energized circuit.
2. Connect the compensation box to one of the channels on the oscilloscope.



3. Install the sensor tip cable to the sensor head.
 - a. Line up the sensor tip cable with the sensor head.
Take care to avoid bending or twisting the sensor tip cable assembly during this process.
 - b. Connect the SMA connector of the sensor tip cable to the sensor head. Use the SMA wrench to tighten the SMA cable to 4 to 5-in lbs.
Use the adjustment tool that was shipped with your probe.

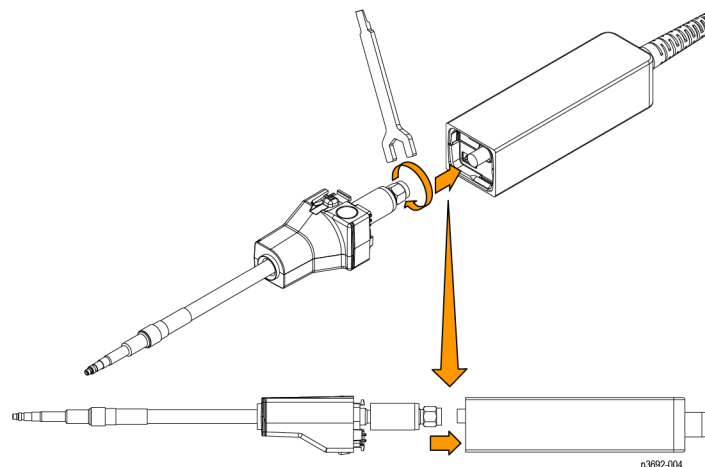


Figure 4: Connecting the sensor tip cable to the sensor head

4. Connect the sensor head to the included bipod or a similar support.

This support keeps the sensor head steady reducing the potential mechanical stresses at the electrical connection point of the DUT. The support also keeps the sensor head away from surrounding circuits and conductive objects to minimize the parasitic capacitive coupling to these surroundings.

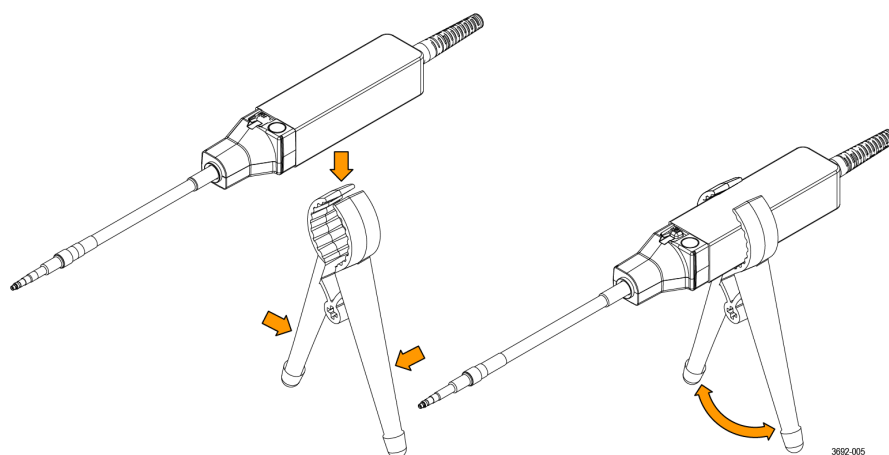


Figure 5: Connect the sensor head to the bipod



Note: To obtain the most accurate measurement, allow the measurement system to warm up for 20 minutes. Then perform the self-calibration before connecting the tip cable to the DUT and taking the measurement.

5. Connect the sensor tip cable end to the DUT. If you are using MMCX sensor tip cable, connect it to an MMCX connector on the DUT or to a square pin adapter on the DUT. The adapters connect to square pins with either 0.100-inch (2.54 mm) spacing or 0.062-inch (1.57 mm) spacing. [Figure 15: Connecting to an adapter on the circuit board with the probe tip tripod](#) on page 40

If you are using one of the square pin sensor tip cables, connect it directly to the square pins on the DUT. [Connecting the sensor tip cables](#) on page 40

6. Set up the controls on the oscilloscope.
7. Apply power to the DUT to take the measurement.

Self-calibration

The TIVP contains a self-calibration function that corrects Gain Accuracy, DC offset, and frequency response. These parameters change as the probe warms up to operating temperature and remains constant once the temperature reaches steady-state. After the probe warms up, self-calibration is recommended when there is a 5°C change in ambient temperature. An indicator LED on the compensation box provides the status of the self-calibration. See the [Controls and indicators](#) on page 26 for more information on the LEDs.

To check the status of the self-calibration programmatically, use the `SELF CAL : STATE? PI` command to determine whether a self-calibration is `RECOMMENDED`, `RUNNING`, or `PASSED`.

Before performing critical measurements, run a self-calibration to ensure the probe is compensated. It takes about 90 seconds to complete.



Note: The sensor tip cable does *not* need to be removed from the test point to successfully complete the self-calibration.

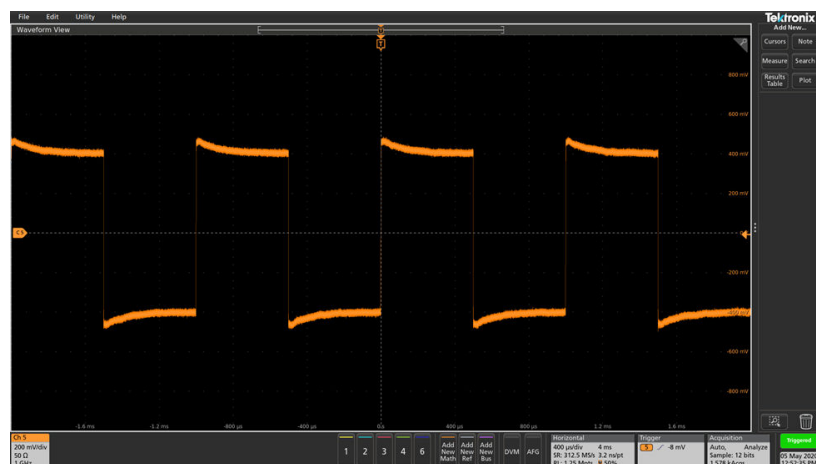
1. Connect probe to an oscilloscope channel.
2. Press the **SELF CAL** button on the probe compensation box. The Self Cal indicator LED will blink while self-calibration is in process.
3. Self-calibration is complete when the indicator LED displays green.

To run the self-calibration programmatically, use the `CH<x> : PROBE : SELF CAL EXECUTE PI` command. The connected channel is specified by "x".

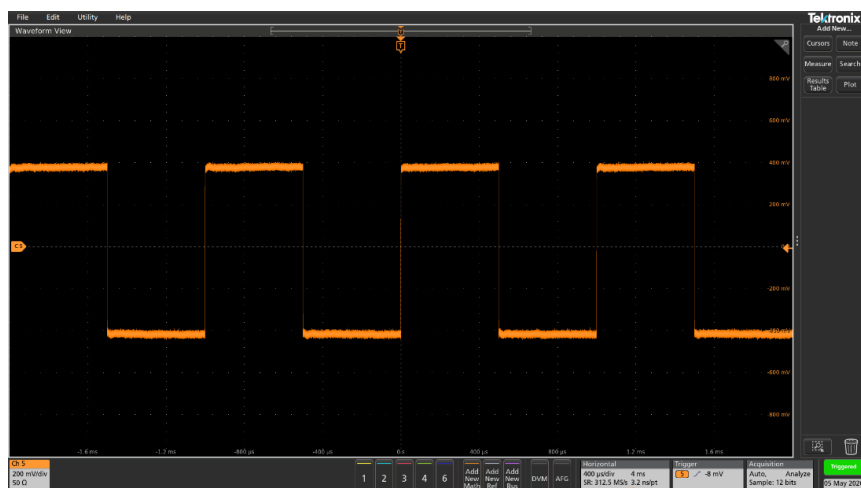
The TIVP probe takes about 20 minutes to warm up. During this time, acquired waveforms may show obvious aberrations. The following screen shot shows how a 1 KHz square wave appears at the beginning of the warm-up period. Notice how the probe appears to be uncompensated.



Note: When moving a probe that has fully warmed up to a new oscilloscope channel, you must give the probe another 5 minutes to warm up on the new channel.



After 20 minutes, most of the aberrations are gone. Self-calibration can be used before the probe reaches its operating temperature, however those self-calibration settings will become invalid a few minutes later as the internal temperature changes.



Self-calibration takes less than 2 minutes to complete. Your signal does not need to be disconnected from the probe head when running self-calibration. The LED next to the **SELF CAL** button on the compensation box will flash yellow during the operation. When complete, the LED will either turn green (passed) or red (failed).

The **SelfCal Status** indicator in the oscilloscope **Probe Setup** menu indicates whether self-calibration is required.



Note: In 4/5/6 Series Mixed Signal Oscilloscopes, commands are available to start and monitor self-calibration and a status query to determine if self-calibration is needed.

AutoZero

AutoZero and self-calibration work on different parts of the measurement system. Self-calibration optimizes measurements through adjusting parameters in the probe. AutoZero is an oscilloscope function and is used when a displayed waveform is not centered correctly (for example; due to a small DC offset error). AutoZero automatically runs after self-calibration. It is not necessary to disconnect your signal from the probe when running a self-calibration. However, when AutoZero is run by itself, the signal must not be present.

Menu button

Press the **MENU** button on the comp box to view the **Probe Setup** menu on the oscilloscope.



Figure 6: Probe Setup menu

Use the menu options on the oscilloscope to change the probe settings.

Ranges

The measurement system has a variety of ranges available for you to select, whether the probe is being used with or without a tip. This allows for tradeoffs to be made between noise and dynamic range depending on the needs of the measurement being made.



CAUTION: To avoid damaging the probe, do not exceed the Peak Voltage rating for a given tip or the probe head. The Maximum Non-Destruct Voltage limit (Peak Voltage) does not increase when the Probe Ranges are changed. For example, the TIVPMX50X limit of ± 250 Vpk is the same for all range settings.

In 4, 5, and 6 Series oscilloscopes, 9 ranges are selectable when **Range Mode** is set to **Manual**. The recommended V/div settings are displayed in the table below. The ranges shown are for the probe SMA input and 1X tip. Multiply the range and V/div setting by the tip attenuation to get the values for a sensor tip cable.

Table 2: Ranges and 4/5/6 Series MSO Volts/div settings

4/5/6 Series MSO probe ranges	Recommended V/div setting
20 mV	2 mV/div
40 mV	5 mV/div
80 mV	10 mV/div
160 mV	20 mV/div
320 mV	50 mV/div
640 mV	100 mV/div
1.28 V	200 mV/div
2.56 V	500 mV/div
5 V	1 V/div

When using a tip, the label of each sensor tip cable shows the maximum dynamic range and the attenuation factor. For example, the TIVPMX10X has a 10X attenuation factor and displays a signal with a ± 50 V differential voltage. When more sensitive ranges are selected, dynamic range is limited. Refer to the Linear differential input voltage range in the specifications table for more information.

Auto Range

In 4, 5, and 6 Series oscilloscopes, the Range Mode is selectable for either Auto Range, or Manual. With the Range Mode set to Auto Range, the probe range is automatically selected when the V/div knob on the oscilloscope is turned. The relationship between probe range and V/div setting matches that shown in [Table 2: Ranges and 4/5/6 Series MSO Volts/div settings](#) on page 31.

Selecting a sensor tip cable



CAUTION: Avoid over-voltage conditions that can damage or degrade the sensor head input termination by selecting the correct sensor tip cable. Selecting the correct sensor tip attenuation factor is crucial to ensure that the sensor head input termination is not degraded or damaged by an over-voltage condition. Select the sensor tip cable that will provide the lowest attenuation possible for the signal being measured.

When selecting a sensor tip cable for a particular application, consider the following questions:

- What is the maximum RMS/Peak Voltage at the test point being measured (for example, under a fault condition)?
- What is the minimum differential loading (input resistance) that my circuit can tolerate?
- How large of a signal do I want to display at one time on the oscilloscope?
- What sensitivity do I need (for example, the minimum V/div setting)?

The following table will help you select the correct sensor tip cable. Start at the top of the table and work down. Choose the first tip that meets all of your criteria.

Table 3: Sensor tip cable selection

Sensor tip cable	Most sensitive V/div setting	Dynamic range	Maximum non-destruct voltage (DC + pk AC) ¹	Differential input resistance
TIVPWS500X	500 mV	±2500 V	3300 Vpk	40 MΩ
TIVPSQ100X	100 mV	±500 V	600 Vpk	9.75 MΩ
TIVPMX50X	50 mV	±250 V	300 Vpk	9.75 MΩ
TIVPMX10X	10 mV	±50 V	250 Vpk	10 MΩ
TIVPMX1X	1 mV	±5 V	100 Vpk / 5 V _{RMS}	1 MΩ / 50 Ω
SMA Input 1 MΩ	1 mV	±5 V	100 Vpk	1 MΩ
SMA Input 50 Ω	1 mV	±5 V	5 V _{RMS}	50 Ω

Deskew

Each probe comes loaded with nominal propagation delay values that can be automatically applied through the **Vertical** menu on the oscilloscope. Deskew accuracy can be improved using a known signal and a deskew fixture. When the timing relationships between waveforms is critical, always deskew your test system with known equipment.

Input offset

The measurement system provides an adjustable input referred offset voltage. This enables viewing a portion of the signal that is off-screen or examining sensitive behavior riding on a larger differential voltage. For example, a 0 V to 600 V step would normally exceed a ±500 V input range. By applying 300 V of offset, the 600 V step is brought into the dynamic range of the probe and can be viewed accurately. Offset is applied by the probe and has a much greater range than the oscilloscope alone.

¹ [Maximum differential input voltage vs frequency derating graphs](#) on page 36

Input coupling AC or DC

The TIVP sensor head contains both DC and DC Reject input coupling modes. By default, DC coupling is enabled; the mode is switchable through the scope interface or PI command.

The DC input coupling setting provides a direct, DC coupled, electrical path in the sensor head; it accepts all types of signals, including unchanging DC voltages, time-varying DC voltages, AC, and combinations of AC and DC.

When DC input coupling is selected, any applied offset is injected at the sensor head and the offset range depends on the attached tip cable attenuation.

DC Reject input coupling setting provides an AC- only path in the sensor head, removing DC offset from any mixed signal to view the AC component of the signal. DC reject is useful when you measure small amplitude signals superimposed on a large differential offset component.

With DC Reject enabled, offset is applied at the oscilloscope input and is limited by the offset capability of the specific Volts/Div setting on the oscilloscope multiplied by the selected tip attenuation.

Voltage range

The TIVP is designed to enable characterization of high frequency circuits with a wide range of differential voltages in the presence of common mode voltages. Understanding the limits and differences between the voltage ratings as discussed in this section is essential to optimize signal fidelity and measurement accuracy.

Although the common mode voltage range of the probe is very large (>60 kV), the differential input range is limited and depends on the tip attenuation, the gain range selected, and the applied offset.

The input voltage conditions are divided into several different input ranges.

Common mode voltage range

TIVP sensor head is optically isolated from earth ground, making the common mode input range >60 kV. The differential input range is more limited and refers to the signal that can be applied across the probe tip, regardless of the common mode voltage.

Differential voltage range refers to the actual *measurement* that will appear on the oscilloscope screen when using IsoVu. For accurate results, the measurement must fall within the range of any applied offset $\pm V_{diff}$ range of the tip. $V_{meas} = V_{offset} \pm V_{diff}$

Offset voltage range

Offset voltage can be applied through the oscilloscope **Vertical** menu settings. The input offset capability of the probe extends from ± 25 V to ± 2500 V depending on the tip used. This offset is applied at the sensor head of probe and can be useful to bring applied signals within the dynamic range (V_{diff}) of the probe.

Maximum non-destruct differential voltage range

The maximum non-destruct differential input range is the maximum differential voltage that can be applied to the input without damaging the probe. This is a DC +peak AC rating (no portion of the differential input signal should exceed this value). The maximum non-destruct differential voltage varies from ± 20 V to ± 2500 V depending of the sensor tip cable being used. Exceeding these levels will cause permanent damage to components of the sensor head. Additionally, the TIVPMX1X and SMA input also have VRMS limits.

Reference information

Specifications

The following tables list the specifications for the measurement system. The specifications are Typical unless noted otherwise.

The performance limits in this specification are valid with these conditions:

- The instrument must be in an environment with temperature, altitude, and humidity within the operating limits described in these specifications.
- The instrument must have had a warm-up period of at least 20 minutes.
- The measurement system is powered from a TekVPI compatible oscilloscope.

Warranted specifications describe guaranteed performance with tolerance limits or certain type-tested requirements.

The performance verification procedures are listed later in this document. [Performance verification procedures](#) on page 44

Overview

Characteristic	TIVP1	TIVP05	TIVP02
Bandwidth	1 GHz	500 MHz	200 MHz
Rise time	450 ps	850 ps	2 ns

Differential Input Voltage Range, Offset Range, Differential Impedance

Use only the sensor tip cables listed.

Sensor tip cable	Differential input voltage range	Offset range	Input impedance
SMA Input (50 Ω mode)	± 5 V	± 25 V	50 Ω N.A.
SMA Input (1 M Ω mode)	± 5 V	± 25 V	1 M Ω 11 pF
TIVPMX10X	± 50 V	± 200 V	10 M Ω 2.8 pF
TIVPMX50X	± 250 V	± 250 V	9.75 M Ω 2.3 pF
TIVPSQ100X	± 500 V	± 500 V	9.75 M Ω 3.5 pF
TIVPWS500X	± 2.5 kV	± 2.5 kV	40 M Ω 2.4 pF
TIVPMX1X	± 5 V	± 25 V	50 Ω or 1 M Ω 28 pF

Common Mode Rejection Ratio Approximately 20 dB lower in ± 5 V Range, except at DC.

Sensor tip cable	DC	1 MHz	100 MHz	200 MHz	500 MHz	1 GHz
SMA Input (50 Ω mode)	160 dB	145 dB	100 dB	100 dB	100 dB	90 dB
SMA Input (1 M Ω mode)	160 dB	145 dB	100 dB	100 dB	100 dB	90 dB
TIVPMX10X	160 dB	115 dB	92 dB	90 dB	85 dB	80 dB
TIVPMX50X	160 dB	110 dB	80 dB	80 dB	80 dB	70 dB
TIVPSQ100X	160 dB	105 dB	60 dB	50 dB	35 dB	25 dB
TIVPWS500X	160 dB	90 dB	50 dB	40 dB	20 dB	10 dB
TIVPMX1X	160 dB	125 dB	115 dB	110 dB	100 dB	90 dB

Maximum Non-Destructive Differential Voltage

Sensor tip cable	V _{pk} (DC + peak AC) ²
SMA Input (50 Ω mode)	5V RMS
SMA Input (1 MΩ mode)	100 V _{pk}
TIVPMX10X	250 V _{pk}
TIVPMX50X	300 V _{pk}
TIVPSQ100X	600 V _{pk}
TIVPWS500X	3300 V _{pk}
TIVPMX1X	5 V RMS (50 Ω), 100 V _{pk} (1 MΩ)

Common mode voltage range 60 kV peak

Common mode input impedance (Typical)

Input resistance Galvanically isolated through the fiber optic connection

Input capacitance ³ <2 pF

DC Gain accuracy

Differential DC gain accuracy <3%

System noise (rms)

Sensor tip cable	±20 mV range (most sensitive)	±320 mV range	±5 V range (widest range)
SMA Input (50 Ω mode)	0.43 mV rms	1.46 mV rms	48 mV rms
SMA Input (1 MΩ mode)	0.43 mV rms	1.46 mV rms	48 mV rms
TIVPMX10X	4.3 mV rms	14.6 mV rms	480 mV rms
TIVPMX50X	21.5 mV rms	73 mV rms	2.4 V rms
TIVPSQ100X	43 mV rms	146 mV rms	4.8 V rms
TIVPWS500X	215 mV rms	730 mV rms	24 V rms

Propagation delay

2 meter cable 18.3 ns

10 meter cable 63.7 ns

Common mode rejection ratio graphs

The ability to measure common mode rejection ratios (CMRR) of the IsoVu system below 100 kHz is limited by the dynamic range of test systems. Due to the optical isolation of the IsoVu sensor head, the DC CMRR performance of all tip cables is expected to be greater than 160 dB.

The following figure shows the typical CMRR values for the supported sensor tip cables.

² Derated with frequency; refer to the Maximum differential input voltage vs. frequency derating graph in the Specifications section of the TIVP Series IsoVu Measurement System User Manual.

³ The capacitance between the sensor head and a reference plane. The sensor head is placed six inches (15.25 cm) above the reference plane.

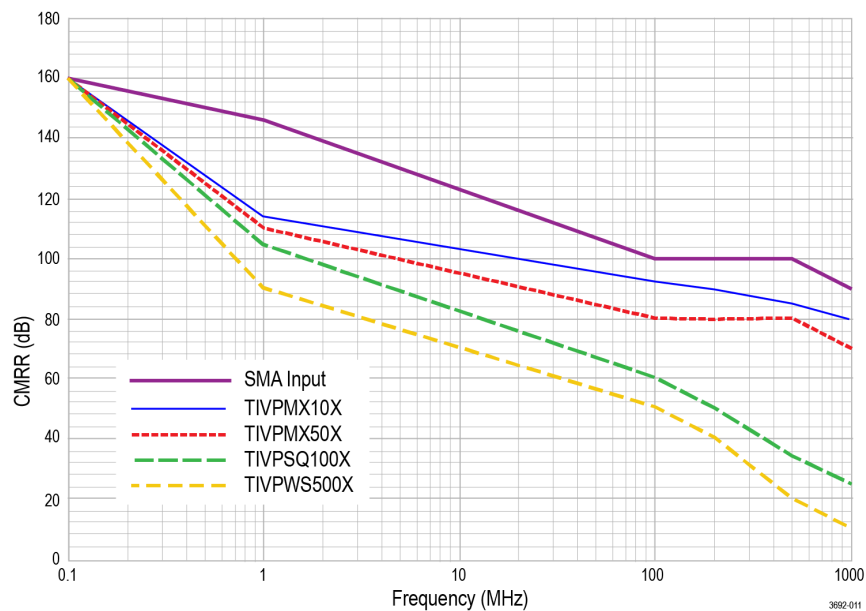


Figure 7: Typical CMRR values for the sensor tip cables

Maximum differential input voltage vs frequency derating graphs

The following figure shows the derating values for the supported sensor tip cables.

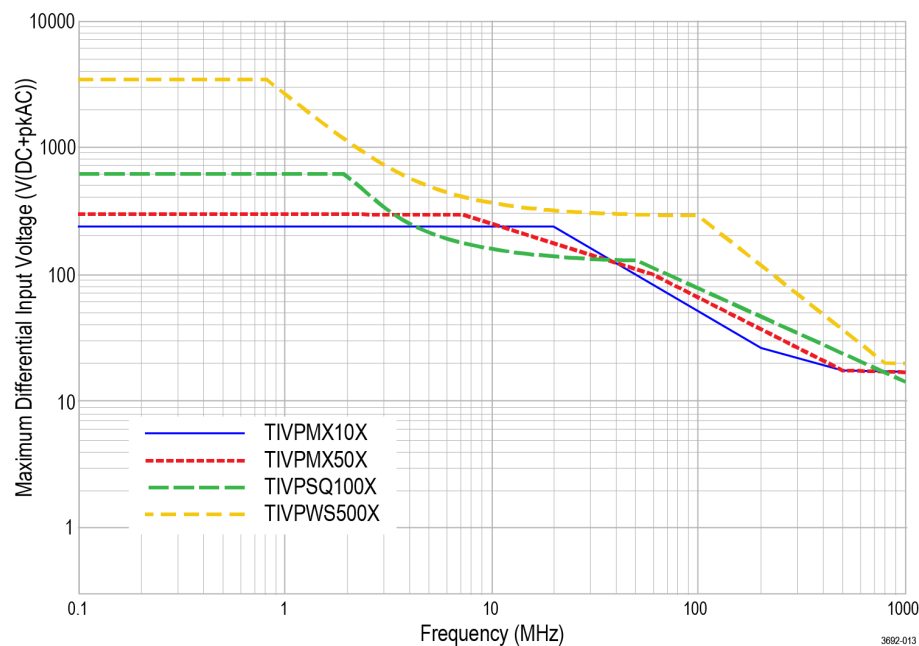


Figure 8: Maximum differential input voltage vs. frequency for the sensor tip cables

Differential input impedance graphs

The following figure shows the differential input impedance vs. frequency values for the supported sensor tip cables.

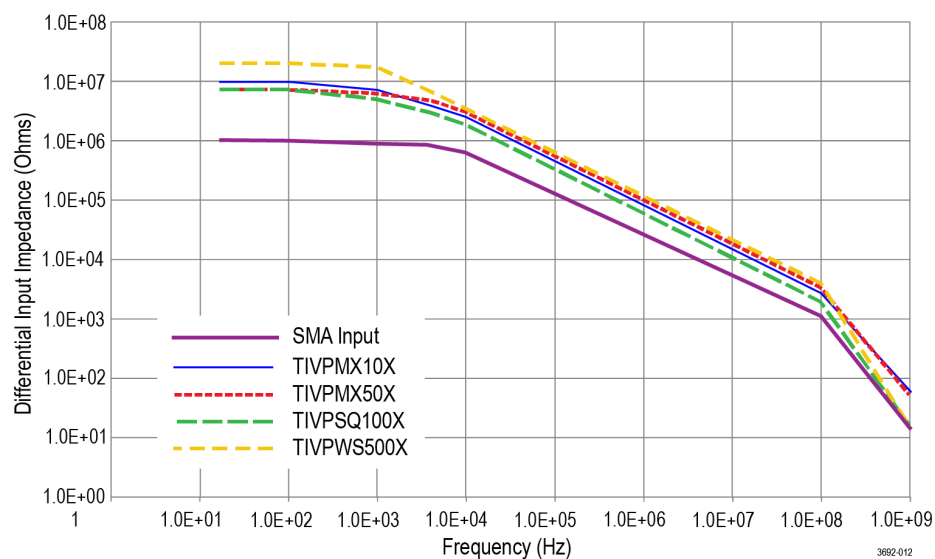


Figure 9: Differential input impedance vs. frequency for the sensor tip cables

TIVP physical specifications

Table 4: Physical specifications

Characteristic	Description
Net weight	Tip cable assembly: 25g (0.055 lb)
(Weight does not include accessories and packaging.)	Probe head: 0.363 kg (0.8 lbs)
	Compensation box: 0.816kg (1.8lbs)
Sensor tip cables	0.025 kg (0.055 lb)
Sensor tip cable length	20.03 cm (7.886 inches)
Fiber cable length	2 meter (6.56 ft)
	10 meter (32.81 ft)

Probe dimensions

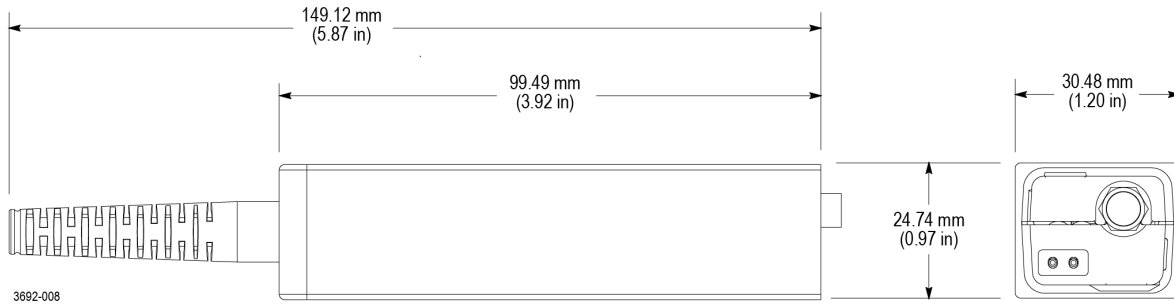


Figure 10: Sensor head

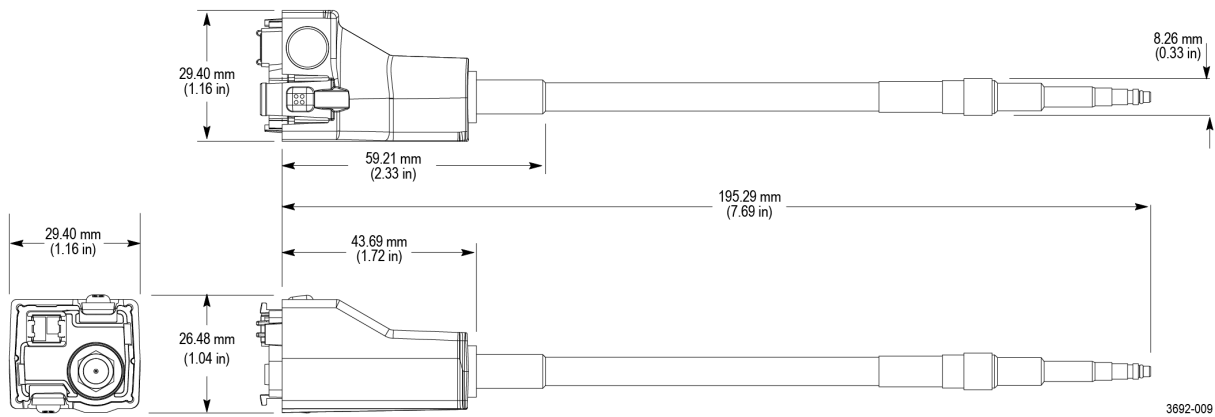


Figure 11: Sensor tip cable

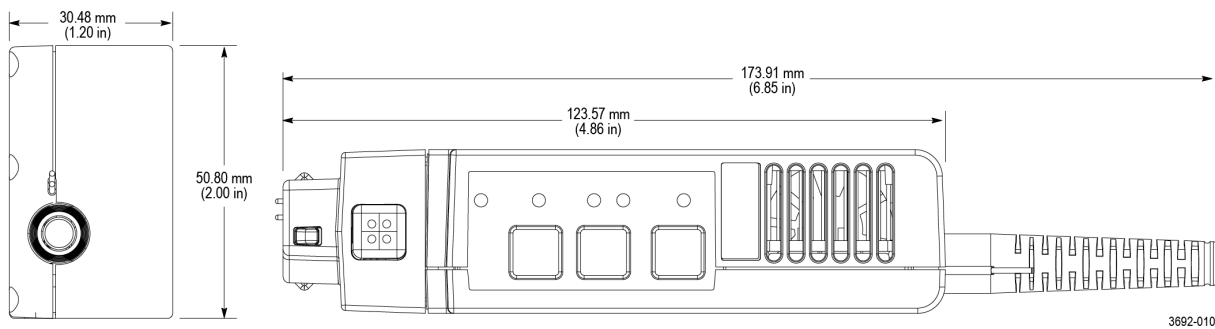


Figure 12: Compensation box

IsoVu measurement system block diagram

The following figure shows a block diagram of the IsoVu measurement system.

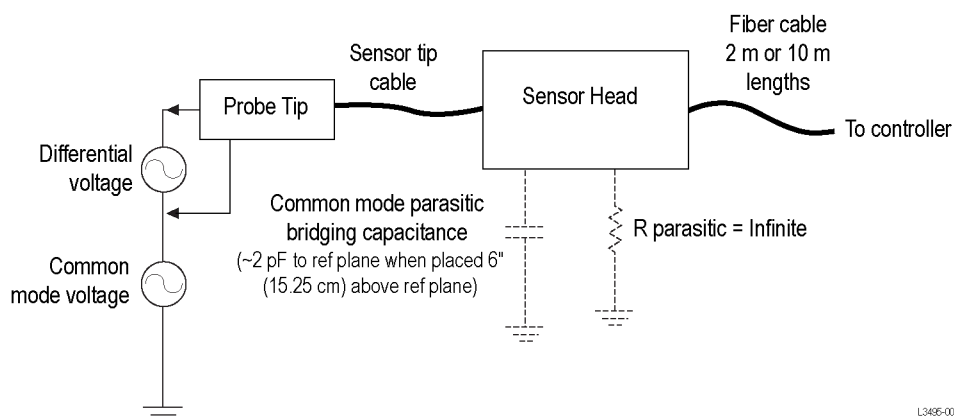


Figure 13: Block diagram

The common mode resistance and capacitance to earth ground is shown in the figure. The common mode resistance is shown as $R_{parasitic}$ and is essentially infinite with the IsoVu measurement system since it is galvanically isolated and can be ignored. The common mode coupling capacitance to earth ground and the surrounding circuit is shown as the Parasitic Bridging Capacitance ($C_{parasitic}$). This parasitic capacitance will be approximately 2 pF when the sensor head is placed six (6) inches (15.25 cm) above a ground plane.

To minimize the effects of common mode capacitive loading consider the following items:

- Whenever possible, choose a reference point in the circuit-under-test that is static potential with respect to earth ground.
- Connect the coaxial (common) shield of the sensor tip cable to the lowest impedance point of the circuit.
- Increasing the physical distance between the sensor head and any conductive surface will reduce the parasitic capacitance.
- When using multiple IsoVu systems to measure different points in the circuit that do not have the same common mode voltages, keep the sensor heads separated to minimize the capacitive coupling.

Connecting the sensor tip cables

Tektronix provides different types of sensor tip cables to connect to the circuit board.

The MMCX sensor tip series connect directly to MMCX connectors on the circuit board or to probe tip adapters installed on the circuit board. [Installing the probe tip adapters](#) on page 40

The square pin series sensor tip cables connect directly to the circuit board as shown in the following figure.

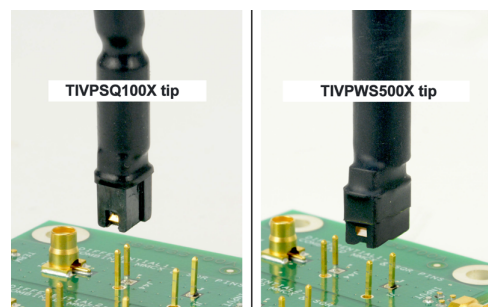


Figure 14: Square pin series sensor tip cables

The SQPIN series sensor tip cables connect to 0.1-inch (2.54 mm) square pins on the circuit board. The WSQPIN series sensor tip cables connect to 0.2-inch (5.08 mm) square pins on the circuit board.

Probe tip tripod

Use the probe tip tripod to connect the sensor tip cables to adapters on the circuit board. This tripod has flexible hinges to easily position the probe tip cable above the adapter on the circuit board. Tektronix recommends gluing the tripod in place on the circuit board to provide additional support for the sensor tip cables. The following figure shows an example of connecting to an adapter on the circuit board with the tripod; it reduces stresses on the test point.

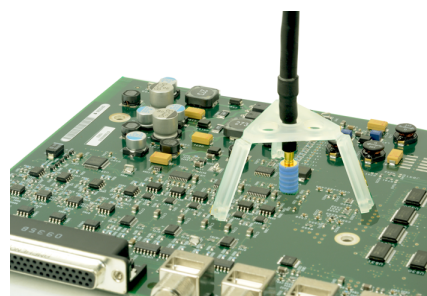


Figure 15: Connecting to an adapter on the circuit board with the probe tip tripod

Installing the probe tip adapters

Tektronix provides two probe tip adapters to connect the MMCX sensor tip cables to pins on the circuit board. The MMCX-to-0.1-inch (2.54 mm) pitch adapter and the MMCX-to-0.062-inch (1.57 mm) pitch adapter.

One end of each adapter has an MMCX socket for connection to an IsoVu MMCX tip cable. The other end of the adapter has a center pin socket and four common (shield) sockets around the outside of the adapter. Notches on the adapters can be used to locate the shield sockets. The procedure for installing these adapters are the same, the main difference is the spacing of the pins on the circuit board.

To install the adapters onto the square pins, line up the center of the adapter with the signal source pin on the circuit board. Use the notch on the adapter to align one of the shield sockets to the common pin on the circuit board. The following figures show examples of lining up the adapters on the circuit board.

To achieve the best electrical performance, especially the CMRR performance and EMI susceptibility, place the probe tip adapter as close as possible to the circuit board.

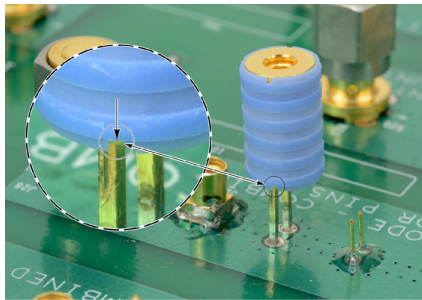


Figure 16: Lining up the MMCX-to-0.1-inch (2.54 mm) adapter on the circuit board

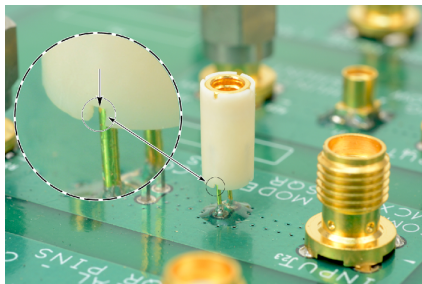


Figure 17: Lining up the MMCX-to-0.062-inch (1.57 mm) adapter on the circuit board

After lining up the adapters gently push down on the adapter to seat it in place on the circuit board.

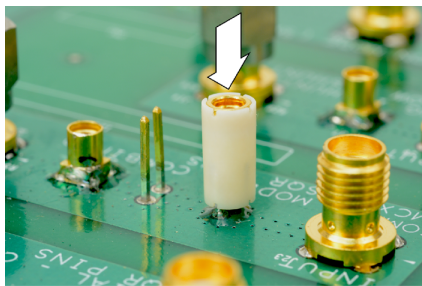


Figure 18: Pushing the MMCX-to-0.062-inch (1.57 mm) adapter in place

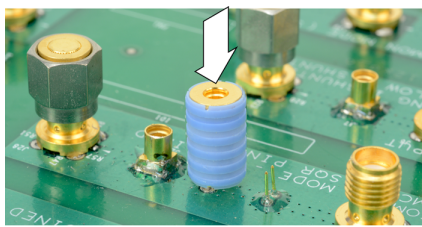


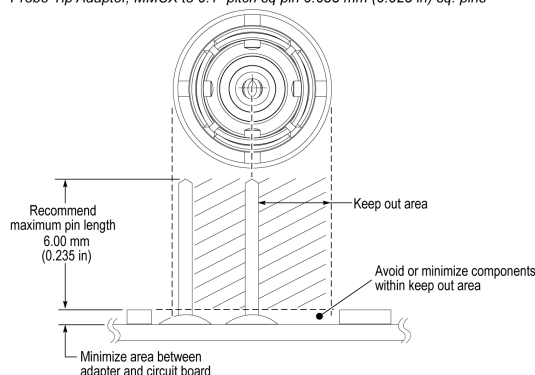
Figure 19: Pushing the MMCX-to-0.1-inch (2.54 mm) adapter in place

When the adapters are firmly in place on the circuit board connect the sensor tip cable to the top of the adapter while using the probe tip tripod to ease the tension off the probe tip cable and adapter. [Figure 15: Connecting to an adapter on the circuit board with the probe tip tripod](#) on page 40

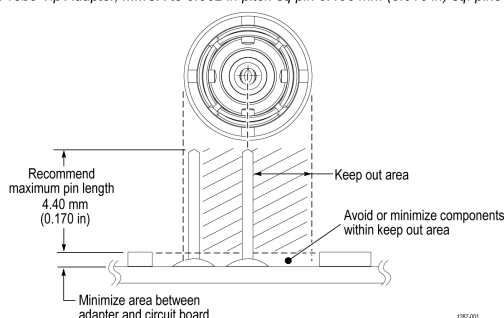
Installing the square pins on the circuit board

The following figure shows the recommended clearance requirements for connecting the adapters to the square pins on the circuit board. The bottoms of the adapters are shown at the top.

Probe Tip Adapter, MMCX to 0.1" pitch sq pin 0.635 mm (0.025 in) sq. pins



Probe Tip Adapter, MMCX to 0.062 in pitch sq pin 0.406 mm (0.016 in) sq. pins



1287-001

Figure 20: Adapter clearance requirements

The 0.025-inch (0.635 mm) square pins should already be located on the circuit board. Some square pins might have headers installed on the circuit board. Tektronix recommends removing the plastic spacer from the square pins to gain closer access to the circuit board as shown in the following figure to achieve the best electrical performance, especially CMRR. You might need to use a pair of tweezers to remove the spacer as shown in the figure.

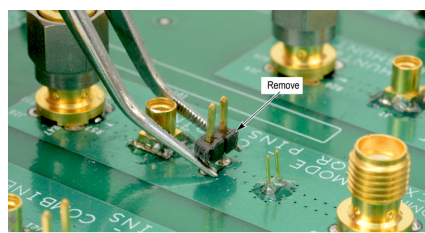


Figure 21: Removing the header from square pins on the circuit board

Tektronix provides a set of solder pins (0.018-inch (0.46 mm) diameter) to install on the circuit board for use with the MMCX to 0.062-inch (1.57 mm) adapter. Use the soldering aid tool accessory (Tektronix part number, 003-1946-xx) to install these pins on the circuit board.



Note: The solder pins are extremely small and can be challenging to handle. Tektronix recommends using tweezers and a magnifying tool when installing the pins on the circuit board.

The solder pins can be installed around a surface mounted component on the circuit board, but adequate clearance should be maintained for a good electrical connection for the adapter. [Figure 20: Adapter clearance requirements](#) on page 42



Note: The coaxial (common) shield of the sensor tip cable and tip adapters should always be connected to the lowest impedance point (usually a circuit common or power supply rail) in the circuit-under-test (relative to the sensor tip cable/center conductor) to obtain the most accurate waveform.

Use the following steps to install the solder pins using the soldering aid on the circuit board:

1. Carefully insert the solder pins into the soldering aid as shown in the following illustration.

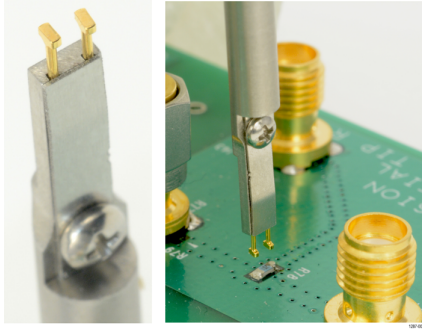


Figure 22: Using the soldering aide to install the square pins on the circuit board

2. Use the soldering aide to hold the square pins in place while soldering the square pins to the circuit board.
3. If necessary apply a small amount of adhesive to further strengthen the connection to the circuit board. However, keep the height of the adhesive to a minimum to provide good electrical contact for the adapter. [Figure 20: Adapter clearance requirements](#) on page 42

User service

Service offerings

Tektronix provides service to cover repair under warranty and other services that are designed to meet your specific service needs.

Whether providing warranty repair service or any of the other services listed below, Tektronix service technicians are well equipped to service the IsoVu measurement system. Services are provided at Tektronix Service Centers and on-site at your facility, depending on your location.

Warranty repair service

Tektronix warrants this product as described in the warranty statements at the front of this manual. Tektronix technicians provide warranty service at most Tektronix service locations worldwide. The Tektronix Web site provides information on all service locations worldwide.

Calibration and repair service

In addition to warranty repair, Tektronix Service offers calibration and other services that provide cost-effective solutions to your service needs and quality standards compliance requirements. Tektronix instruments are supported worldwide by the leading-edge design, manufacturing, and service resources of Tektronix to provide the best possible service.

Preventive maintenance



CAUTION: To prevent damage to the measurement system, do not expose it to sprays, liquids, or solvents. Avoid getting moisture inside the comp box or sensor head when cleaning the exterior.

Clean the exterior surfaces with a dry, lint-free cloth or a soft-bristle brush. If dirt remains, use a soft cloth or swab dampened with a 75% isopropyl alcohol solution. Use only enough solution to dampen the cloth or swab. Do not use abrasive compounds on any part of the instrument.

Performance verification procedures

Use the following procedures to verify the performance of the IsoVu measurement system. Before beginning the procedures, photocopy the test record and use it to record the performance results. [Test record](#) on page 46

Required equipment

The equipment required to perform the performance verification procedures are shown in the following table.

Table 5: Required equipment for performance verification

Description	Minimum requirements	Example product
Supported oscilloscope with TekVPI interface	50 Ω input support, fully compatible with TekVPI interface	Tektronix 5 Series MSO
SMA male short circuit connector cap (optional)	Internally shorted, copper plated contact	Fairview Microwave SC2135

Preparation

Prepare the equipment as follows:

1. Turn on the TekVPI oscilloscope.
2. Connect the TIVP probe to the oscilloscope on CH 1.
 - Remove any TIVP probe tip, if attached
 - Attach SMA Male short circuit cap (optional)

3. Allow the test equipment to warm up for 30 minutes at an ambient temperature of about 20 °C.

System RMS Noise

This procedure verifies that the TIVP Series IsoVu measurement system is functioning and meets the warranted noise specification. The noise will be measured with no input signal at the most sensitive range.



Note: This procedure is valid for all versions of the TIVP Series IsoVu measurement systems

Setup the Measurement System

Procedure

1. Perform a **Default Setup** action.
2. Run **Signal Path Compensation** if recommended in **Utility > Calibration...**
3. Run the self-calibration routine. [Self-calibration](#) on page 29
4. Enable the TIVP Channel and use the following **Vertical** menu settings.
 - Vertical Scale: **2mV/div**
 - Set Termination: **50 Ω**
 - Coupling: **DC**
 - Bandwidth: **20 MHz**
5. Edit **Trigger** menu settings.
 - Type: **Edge**
 - Source: **AC Line**
 - Slope: **Rising**
 - Level: **0 V**
 - Coupling: **DC**
6. Edit the **Horizontal** menu settings.
 - Horizontal Scale: **10 ns/div.**
 - Record Length: **10k**
 - Single Sequence Stop After: **50 Acquisitions**
7. Add a measurement with the following settings.
 - Amplitude Measurement: **AC RMS**
 - Source: **CH 1**

Perform the measurement

Procedure

1. Press the **Single / Seq** button.
2. After 50 acquisitions, record the AC RMS measurement result in the test record table.

Test record

Use the test record table for recording the results of the performance verification procedures.

Table 6: Test record table

Model number:	Procedure performed by:
Serial number:	Date:

System RMS noise performance check			
Probe	Range	Limit	Test result
TIVP1	20 mV	1 mV RMS	
TIVP05	20 mV	0.7 mV RMS	
TIVP02	20 mV	0.4 mV RMS	

Troubleshooting and error conditions

The following tables describes the state of each LED and lists possible problems that you might encounter when taking measurements with a TIVP Series isolated probe. Use the tables as a quick troubleshooting reference before contacting Tektronix for service.

Table 7: STATUS LED descriptions

LED	Status	Action
 Green (Solid)	Normal operation	-
 Green (Blinking)	Bulk power failure	Try unplugging and plugging back in. Inspect probe/scope interface. Service of probe may be required.
 Red (Solid)	Probe application failure	Try unplugging and plugging back in. Service of probe may be required.
 Red (Blinking)	Probe application failure and bulk power failure	Try unplugging and plugging back in. Inspect probe/scope interface. Service of probe and/or scope may be required.
 Red (Blinking ••–)	Self-Test failure No Power to probe head	Try unplugging and plugging back in. Service of probe may be required.

Table 8: SELF CAL LED descriptions

LED	Status
 Green (Solid)	Self-calibration completed successfully
 Amber (Intermittent flashing)	Self-calibration currently in progress
 Red (Solid)	Self-calibration failed
 Amber (Solid)	Self-calibration recommended Internal probe temperatures or other settings have invalidated the previous Self Cal.

Table 9: INPUT LED descriptions

LED	Status
 50 Ω	Sensor head SMA connector is terminated in 50 Ω ± 5 V input range
 1 M Ω	Sensor head SMA connector is terminated in 1 M Ω ± 5 V input range
Neither	Sensor head has tip attached (switching input termination disabled)

Table 10: ALT Mode LED description

LED	Status
 Magenta (Flashing)	The probe compensation box is near its maximum operating temperature. Additional cooling, such as an external fan, may be required.

Table 11: Measurement problems and possible solutions

Problem	Remedy
DC offset is present in signal	- Run SELF CAL - Ensure the input signal is within the selected tip's dynamic range
The Square Wave edge appears "smoothed", rolled off, or uncompensated	- Run SELF CAL - Make sure the scope bandwidth filter is set to full bandwidth - Make sure the input signal is not overdriving the probe input
The measured amplitude is smaller than expected	- The input signal may be "railed" - Make sure the input signal is within the dynamic range of the selected probe tip - Apply offset to bring the input signal within the dynamic range of the selected probe tip
DC measurement inaccuracy	- Run SELF CAL - Set the record length to at least 200 μs (longer is better) to allow time for the optical components to settle on the correct DC value
There is too much noise and you cannot accurately measure small signals	- Select a sensor tip cable with lower attenuation - Set the oscilloscope vertical scale to a smaller value - Manually select a lower range to lower noise
There is no signal detected; the waveform is a flat line	- Remove the sensor tip cable and check its continuity, referencing the input impedance table - Try putting a signal directly into the probe head SMA to check if just the probe tip or the probe itself is broken
The probe head loses power intermittently	- Make sure the probe head is within its operating temperature range - Add external cooling; such as a small desktop fan
There is too much common mode noise	- Try to remove any accessories, flying leads, or exposed wires between the test point and the probe tip - Use an MMCX tip with an MMCX test point either designed into the board or as an unplanned test point

Repack the measurement system for shipment

If you need to return the measurement system to Tektronix for repair, use the original packaging. If this is unavailable or not fit for use, contact your Tektronix representative to obtain new packaging.

When you return the measurement system to Tektronix, attach a tag showing the following information:

- Name of the product owner
- Address of the owner
- Instrument serial number
- A description of problems encountered and/or service required

Remote programming

This appendix describes commands and queries that can be sent to the sensor head when attached to a Tektronix oscilloscope. Long-form and short-form keywords are indicated with upper/lower case letters. The commands and queries are supported by most oscilloscopes; differences in supporting oscilloscopes, if any, are described with the commands.

For additional information, refer to the programmer documentation for your oscilloscope.

Command list

A list of the commands supported by TIVP in alphabetical order.

CH<x>:PRObe? (Query Only)

This query-only command returns all information concerning the probe that is attached to the specified channel. The channel is specified by x.

Syntax CH<x>:PRObe?

Examples CH2:PROBE? might return 1.0000E-01; RESISTANCE 1.0000E+07;UNITS "V";ID:TYPE "10X" 'SERNUMBER "N/A" for a 10X probe, indicating that (among other parameters) the attenuation factor for the probe attached to Channel 2 is 100.0 mV (assuming that probe units are set to volts).

CH<x>:PRObe:AUTOZero (No Query Form)

This command executes the AutoZero function. The operation is entirely performed by the oscilloscope. The channel is specified by x.

Refer to the self-calibration procedure for information on performing the self calibration. [Self-calibration](#) on page 29

Syntax CH<x>:PRObe:AUTOZero EXECute

Arguments EXECute sets the probe attached to the specified channel to AutoZero.

Examples CH1:PROBE:AUTOZERO EXECUTE sets the probe attached to the Channel 1 to autozero.

CH<x>:PRObe:FORCEDRange

The command selects the dynamic range of probe (1 of 9) in +/-V. It is dependent on the attached probe tip. The channel is specified by x. The command should only be used when CH<x> : PROBECONTROL is set to MANUAL.

Table 12: Probe tip cables and dynamic ranges

Probe tip cable	Dynamic Range +/-V
No tip or 1X tip	0.02 0.04 0.08 0.16 0.32 0.64 1.28 2.56 5.0
10X	0.2 0.4 0.8 1.6 3.2 6.4 12.8 25.6 50.0
50X	1.0 2.0 4.0 8.0 16.0 32.0 64.0 128.0 250.0
100X	2.0 4.0 8.0 16.0 32.0 64.0 128.0 256.0 500.0
500X	10.0 20.0 40.0 80.0 160.0 320.0 640.0 1280.0 2500.0

The query returns the dynamic range of the probe tip in +/-V.

Syntax	CH2:PRObe:FORCEDRange <NR3> CH2:PRObe:FORCEDRange?
Arguments	<NR3> specifies the probe dynamic range
Examples	If a current probe is attached to the Channel 1 input, CH1:PROBE:FORCEDRANGE 5.0 sets the attached probe to its 5 V range. CH3:PROBE:FORCEDRANGE? might return 5.0000, indicating that the range of the probe attached to the Channel 3 is set to 5 V.

CH<x>:PRObe:GAIN? (Query Only)

The command returns the gain factor of the currently selected range (inverse of attenuation). The channel is specified by x.

Syntax	CH<x>:PRObe:GAIN?
Examples	CH2:PROBE:GAIN? might return 100.0000E-3, indicating that the attached 10X probe delivers 0.1 V to the Channel 2 BNC for every 1.0 V applied to the probe input.

CH<x>:PRObe:ID? (Query Only)

This query-only command returns the type and serial number of the probe that is attached to the specified channel. The channel is specified by x.

Syntax	CH<x>:PRObe:ID?
Examples	CH2:PROBE:ID? might return "B010289"; "TIVP1", indicating that a TIVP1 probe with serial number B010289 is attached to Channel 2.

CH<x>:PRObe:ID:SErnumber? (Query Only)

This query-only command returns the serial number of the probe that is attached to the specified channel. The channel is specified by x.



Note: For Level 0 and 1 probes, the serial number will be "N/A".

Syntax `CH<x>:PRObe:ID:SErnumber?`

Examples `CH1:PROBE:ID:SERNUMBER?` might return "B010289", indicating that the serial number of the probe attached to Channel 1 is B010289.

CH<x>:PRObe:ID:TYPe? (Query Only)

This query-only command returns the type of probe that is attached to the specified channel. The channel is specified by x.

Syntax `CH<x>:PRObe:ID:TYPe?`

Examples `CH1:PROBE:ID:TYPE?` might return "TIVP1", indicating that a TIVP1 current probe is attached to Channel 1.

CH<x>:PRObe:RESistance? (Query Only)

This query-only command returns the resistance of the probe that is attached to the specified channel. The channel is specified by x.

Syntax `CH<x>:PRObe:RESistance?`

Examples `CH2:PROBE:RESISTANCE?` might return `10.00000E+6`, indicating that the input resistance of the probe attached to Channel 2 is 10 MΩ. This query only returns valid data when a tip is attached. Otherwise, -1.0000 is returned.

CH<x>:PRObe:SELFCal:State? (Query Only)

This query-only command returns the self-calibration state of RECOMMENDED, RUNNING, or PASSED. The channel is specified by x.

Syntax `CH<x>:PRObe:SELFCal:State?`

Examples `CH1:PRObe:SELFCal:State?` might return `RUNNING`, indicating that the Channel 1 probe is currently running a self-calibration.

CH<x>:PRObe:SELFCal

This query-only command initiates self-calibration on the probe. The channel is specified by x.

Syntax `CH<x>:PRObe:SELFCal EXECUTE`

Examples `CH1:PRObe:SELFCal EXECUTE` runs self-calibration on the Channel 1 probe.

CH<x>:PRObe:SET

This command sets or queries the probe input resistance for the specified channel. The channel is specified by x.

Syntax	<code>CH<x>:PRObe:SET {"50ohms ON" "50ohms OFF"}</code> <code>CH<x>:PRObe:SET?</code>
Arguments	The text in quotes is not case sensitive. For returns, the case is the same as the last command received. "50ohms ON" sets the input termination (when no tip is attached) to 50 Ω . "50ohms OFF" turns off the 50 Ω input termination.
Examples	<code>CH6:PRObe:SET "50ohms ON"</code> sets the input termination of channel 6 to 50 Ω . <code>CH6:PRObe:SET?</code> might return "50ohms OFF", indicating that the input termination on channel 6 is off.

CH<x>:PRObe:STATus? (Query Only)

This command queries the probe unsigned integer error value. The channel is specified by x.

Conditions	Requires a probe that supports the relevant error messages.
Syntax	<code>CH<x>:PRObe:STATus?</code>
Returns	Returns an integer number that represents the sum total of binary error bits B0 – B15. The error bits are not displayed; they are concatenated into the integer value. The following is a list of the error for each bit. • B0 – Probe disabled • B1 – Jaws open • B2 – Over range • B3 – Probe temperature out of limits • B4 – Degauss needed • B5 – Probe tip missing • B6 – Probe tip failed • B7 – Probe tip not supported • B8 – self-calibration is needed or recommended (the query will return 256 in decimal format) • B9 through B15 – Reserved
Examples	<code>CH4:PROBE:STATus?</code> might return 2, indicating that the probe is reporting an open jaws error.

CH<x>:PRObe:UNIts? (Query Only)

This query-only command returns a string describing the units of measure for the probe attached to the specified channel. The channel is specified by x.

Syntax	<code>CH<x>:PRObe:UNIts?</code>
Examples	<code>CH4:PROBE:UNITS?</code> might return "V", indicating that the unit of measure for the probe attached to Channel 4 is Volts.

CH<x>:PROBECOntrol

This command sets or queries multirange probe range-control policy preference of the probe that is attached to CH<x>. The channel number is specified by x.

Syntax	CH<x>:PROBECOntrol {AUTO MANual} CH<x>:PROBECOntrol?
Arguments	AUTO sets the values. The probe range is automatically calculated. MANual allows you to select various valid values for the probe connected to a particular channel.
Examples	CH2:PROBECOntrol AUTO sets the values and the probe range is automatically calculated. CH2:PROBECOntrol? might return MANUAL indicating that you can select various valid values for the probe connected to channel 2.

CH<x>:PROBEFunc:EXTAtten

This command is used to specify the attenuation value as a multiplier to the given scale factor on the specified channel. The channel is specified by x.

The query form of this command returns the user-specified attenuation.

Syntax	CH<x>:PROBEFunc:EXTAtten <NR3> CH<x>:PROBEFunc:EXTAtten?
Arguments	<NR3> is the attenuation value, which is specified as a multiplier in the range from 1.00E-10 to 1.00E+10.
Examples	CH1:PROBEFunc:EXTATTEN 167.00E-3 specifies an external attenuation, which is connected between the your input signal and the input of the probe attached to Channel 1. CH2:PROBEFunc:EXTATTEN? might return 1.0000E+00, indicating that the probe attached to Channel 2 is connected directly to the user's signal.

CH<x>:PROBEFunc:EXTDBatten

This command sets or queries the input-output ratio (expressed in decibel units) of external attenuation or gain between the signal and the instrument input channels. The channel is specified by x.

The query form of this command returns the user-specified attenuation in decibels.

Syntax	CH<x>:PROBEFunc:EXTDBatten <NR3> CH<x>:PROBEFunc:EXTDBatten?
Arguments	<NR3> is the attenuation value, which is specified in the range from -200.00 dB to 200.00 dB.
Examples	CH3:PROBEFunc:EXTDBATTEN 2.5 specifies an external 2.5 dB attenuator on Channel 3. CH1:PROBEFunc:EXTDBATTEN? might return 2.5000E+00, indicating that the attenuation for Channel 1 is 2.5 dB.

CH<x>:PROBEFunc:EXTUnits

This command sets the unit of measurement for the external attenuator of the specified channel. The channel is specified by x. The alternate units are used if they are enabled. Use the CH<x>:PROBEFunc:EXTUnits:STATE command to enable or disable the alternate units.

Syntax	CH<x>:PROBEFunc:EXTUnits <QString> CH<x>:PROBEFunc:EXTUnits?
Arguments	<QString> indicates the attenuation unit of measurement for the specified channel.
Examples	CH4:PROBEFunc:EXTUNITS "Pascals" sets the unit of measurement for the Channel 4 external attenuator.

CH2:PROBEFunc:EXTUnits:STATE? might return "Pascals", indicating that the Channel 2 external attenuator unit of measurement is Pascals.

CH<x>:PROBEFunc:EXTUnits:STATE

This command sets or queries the custom units enable state for the specified channel. The channel is specified by x.

Syntax	CH<x>:PROBEFunc:EXTUnits:STATE {ON OFF <NR1>} CH<x>:PROBEFunc:EXTUnits:STATE?
Arguments	OFF argument turns off external units. ON argument turns on external units. <NR1> = 0 turns off external units; any other value turns on external units.
Examples	CH2:PROBEFunc:EXTUnits:STATE ON turns on external units. CH2:PROBEFunc:EXTUnits:STATE? might return 0, indicating that external units are off for the specified channel.

CH<x>:PROBE:DYNAMICRANGE? (Query Only)

This command queries the dynamic range of the probe that is attached to the specified channel. The channel is specified by x.

Syntax	CH<x>:PROBE:DYNAMICRANGE?
Returns	The returned value is the delta between the current minimum and maximum range with some tolerance. It is also the delta between the probe range indicators (if currently displayed).
Examples	CH1:PROBE:DYNAMICRANGE? might return 1.3056, indicating that the dynamic range of the probe attached to the Channel 1 is set to 1.3056 V.

Index

A

accessories
 optional [21](#)
 standard [20](#), [21](#)
Auto Range [32](#)

B

bend radius
 fiber-optic cables [23](#)
 sensor tip cables [23](#)
block diagram [39](#)

C

cable care [23](#)
cable flags [26](#)
cable handling practices [23](#)
CMRR [35](#)
common mode rejection ratios [35](#)
comp box [19](#)
comp box buttons
 menu [31](#)
connecting the measurement system [27](#)

D

DC CMRR [35](#)
deskew [32](#)
differential input impedance graphs [36](#)

E

environmental considerations [24](#)
error conditions [47](#)

F

fiber-optic cable
 safe handling practices [23](#)
Freescale Kinetis Design Studio [12](#)

I

IAR Embedded Workbench for ARM [12](#)
input offset [32](#)
input specifications [24](#)
installing the probe tip adapters [40](#)
lowegian ScopellIR [13](#)
IsoVu [18](#)

L

laser certification [18](#)

M

measurement system setup [45](#)
menu button [31](#)
MMCX connectors [19](#)
models [20](#)

O

operating requirements [23](#)
optional accessories [21](#)

P

packaging [48](#)
performance verification
 procedures [44](#)
 required equipment [44](#)
 system RMS noise [45](#)
 test record [46](#)
physical specifications [37](#)
probe tip tripod [40](#)
product description [19](#)
propagation delay [32](#)

R

repackaging [48](#)
RF burn area [25](#)

S

self cal
 AutoZero [30](#)
 requirements [29](#)
self-calibration [29](#)
sensor head
 description [19](#)
sensor tip cable
 installation [27](#)
 labels [26](#)
 selection considerations [32](#)
sensor tip cables
 bend radius [23](#)
service offerings [44](#)
solder aide [42](#)
solder pin installation [42](#)

specifications [34](#)
square pin adapters [28](#)
square pin connectors [19](#)
standard accessories [20](#), [21](#)
supported oscilloscopes [20](#)

T

test record [46](#)
TIVP01L [20](#)
TIVP02 [20](#)
TIVP02L [20](#)
TIVP05 [20](#)
TIVP05L [20](#)
TIVP1 [20](#)
troubleshooting [47](#)

U

user service [44](#)

V

voltage vs. frequency derating graphs [36](#)

W

warranty repair service [44](#)